

**IDS WORKSHOP 2012** 

# A review of some systematic errors observed in the Precision Orbit Determination of recent DORIS satellites

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Systematic errors (along-track bias, macromodels signatures, network signatures) that might be of interest for the IDS analysts

 Provide updated figures with the latest standards (GDR-D) and satellites (HY2A)

#### DORIS ORBITS :

- Laser statistics
- Jason2 / HY2A GPS to DORIS comparison
- Updated Empiricals and Macromodels

#### DORIS NETWORK

- Annual Signatures on specific beacons
- Phase maps ?



#### **SLR statistics on DORIS-only orbits**



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## Number of passes



### Average along-track bias per pass



5

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#### Average range bias per pass



## Standard deviation of range bias per pass



## **RMS** after fit



#### **SLR Residuals as a function of elevation**



## **Comparison of GPS Vs DORIS orbits**



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## DORIS-based 24 hr 1/rev , along-track



### DORIS-based 24 hr 1/rev , cross-track



## **RMS of DORIS Residuals**



#### **DORIS RMS per Beacon**



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0.3

0.2*--*-

#### **DORIS RMS per Beacon**

Monthly Median RMS per pass of CADB residuals on DORIS-only orbits 1.0 Cryosat Jason-2 0.9 HY2A 0.8 Envisat Jason-1 0.7 % ៣.6 0.5 0.4 0.3 0.2*—* 2004 2005 2006 2007 2008 2009 2010 2011 2012 2013



Average SLR / DORIS Along track bias is largely reduced (< 2 cm) using the latest DORIS datasets

- Accuracy of DORIS-only dynamic orbits estimated by SLR residuals is similar for different satellites :
  - better than 2 cm RMS radial, ~5 cm along-track and cross-track
- Good agreement between DORIS-only and GPS-only dynamic orbits
- Macromodels for most recent satellites (Cryosat-2, HY2A) have margins for improvement
- DORIS residuals after JASON-1 orbit change should be carefully monitored

## PROSPECTS

Extend the phase-residual maps derived from Jason-2 with Cryosat-2 and HY2A data – and test impact on phase residuals of proposed new PCO/PCV for STAREC Antennas

http://ids-doris.org/documents/report/AWG200903/SOD\_PhaseResidualMapsJason2AllStationsCy001\_017.pdf





#### Thanks !

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