

Near-Real-Time DORIS Data for GNSS-based Ionospheric Maps

Validation and Combination

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- ▶ Background and Motivation
- ▶ DORIS dSTEC analysis concepts
- ▶ Data sets and analysis results

NRT DORIS data for GIM validation

NRT DORIS data for GIM combination

- ▶ Summary and conclusions





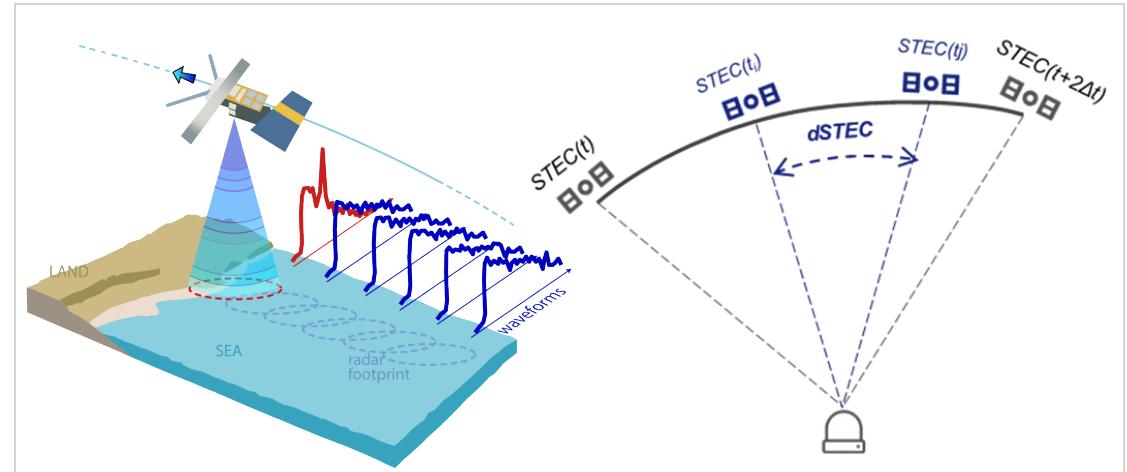
Validation of Real-Time Global Ionospheric Maps (RT-GIMs)

► Self-consistency check

- GNSS-derived STEC: code smoothing or precise point positioning (PPP) derived, S/R DCB removed.
- **GNSS-derived dSTEC**: carrier phase geometry-free combination derived, differential STEC b.w.t. two epochs along individual continuous arcs, low level of observation noises.
- GNSS derived STEC and dSTEC are available in real-time (few seconds in time latency).

► External-consistency check

- Altimetry-derived VTECs, available over the oceanic regions.
- Fully independent to GNSS measurements.
- **Near-real-time altimetry VTECs provided by Jason-3 (~3 hours in latency)**





Using DORIS Data to Validate and Combine GNSS generated Ionospheric Maps

- ▶ DORIS data: valuable and external data sources to examine the Earth's ionosphere.
- ▶ Homogeneous distribution of DORIS ground beacons, covering continental and oceanic regions.
- ▶ DORIS data are available from 8 satellite missions: CRYOSAT-2, HY-2C, HY-2D, Jason-3, SARAL, Sentinel-3A, Sentinel-3B and Sentinel-6A
- ▶ The large relative frequency ratio (~5) between two frequencies of DORIS: more sensitive to detect the ionospheric information and less prone to measurement noises.
- ▶ The standardization of DORIS data formats, i.e., RINEX DORIS 3.0, similar to the existing GNSS RINEX format.
- ▶ The decreasing time latency in obtaining DORIS data (~3 hours for Jason-3 DORIS data).

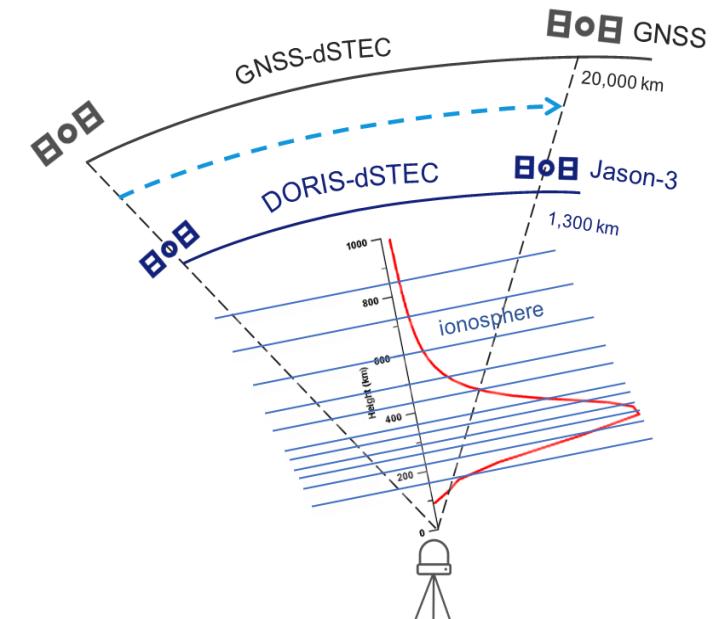




GNSS-dSTEC analysis concept

- ▶ **GNSS-dSTEC:** the differential phase STEC along a continuous arc referring to the highest satellite elevation (Hernández-Pajares et al. 2017).
- ▶ Only dual-frequency carrier phase measurements used (geometry-free linear combination).
- ▶ Avoiding the negative effects of amplified pseudorange noises as well as the intra-day variation of receiver biases in *code-smoothing technique* derived STEC/VTEC.
- ▶ GNSS-dSTEC used for the IGS rapid/final TEC maps combination for more than 20 years

$$dSTEC_{GNSS}(t) = 40.3 \times (f_1^{-2} - f_2^{-2}) \times [L_I(t) - L_I(t_{E_{\max}})]$$



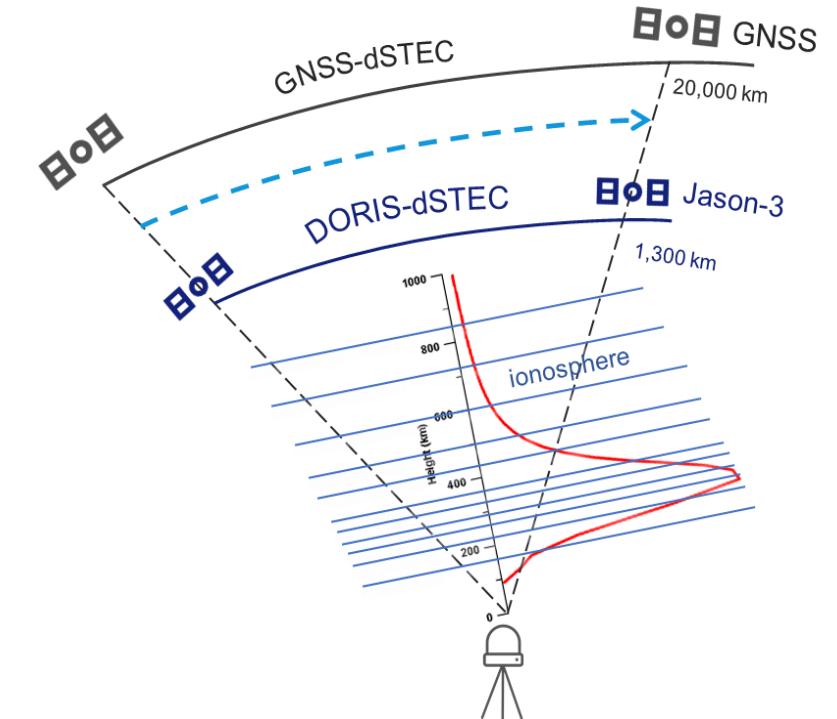


DORIS-dSTEC analysis concept

- ▶ The calculation of DORIS-dSTEC is very similar to that of GNSS-dSTEC, generated based on dual-frequency DORIS carrier phase measurements.
- ▶ Containing dSTEC information to the height of LEO satellites, e.g. ~1,300 km for Jason-3.

$$dSTEC_{DORIS}(t) = 40.3 \times (f_1^{-2} - f_2^{-2}) \times [L_I(t) - L_I(t_{E\max}) - (\Delta D(t) - \Delta D(t_{E\max}))]$$

ΔD denotes the geometry correction (i.e., the PCO correction)





Precision analysis of DORIS/GNSS derived dSTEC information

- ▶ Ignoring the correlation b.w.t. L1/L2 carrier phase measurements, the theoretical precision of DORIS or GNSS dSTEC can be estimated by

$$\begin{cases} \sigma_{dSTEC}^2 = 2\mu^2\sigma_{LI}^2 \\ \sigma_{LI}^2 \approx \sigma_{L_1}^2 + \sigma_{L_2}^2 \end{cases}$$

σ_{LI} denotes the precision of geometry-free linear combination of dual-frequency DORIS/GNSS phase measurements

- ▶ Precision of DORIS-dSTEC reaches **0.028 TECu** ($\sigma_{L1}=1.5$ mm and $\sigma_{L2}=7.5$ mm)
- ▶ Precision of GNSS-dSTEC is about 0.25 TECu ($\sigma_{L1}=\sigma_{L2}=2.0$ mm)
- ▶ The precision of those derived dSTEC **benefits from the large frequency difference** (i.e., $f_1 - f_2$)
- ▶ Overall, the theoretical precision of DORIS-dSTEC is about 10 times better than GNSS-dSTEC

(Liu, Wang et al. 2023)



Overview of RT-GIMs provided by different analysis centers (ACs)

AC	Caster	Mountpoint	Interval
CAS	products.igs-ip.net:2101	SSRC00CAS1 (<i>IGS-SSR</i> ¹)	60s
CNES	products.igs-ip.net:2101	SSRC00CNE1 (<i>IGS-SSR</i>)	60s
UPC	products.igs-ip.net:2101	IONO00UPC1 (<i>IGS-SSR</i>)	15s
WHU	58.49.94.212:2101	IONO00WHU0 (<i>RTCM-SSR</i> ²)	60s
UPC-combined*	products.igs-ip.net:2101	IONO00IGS0 (<i>IGS-SSR</i>)	15s
CAS-combined*	products.igs-ip.net:2101	IONO01IGS0 (<i>RTCM-SSR</i>)	60s
		IONO01IGS0 (<i>IGS-SSR</i>)	

* Combined RT-GIMs using *ground based* RT-GNSS data streams

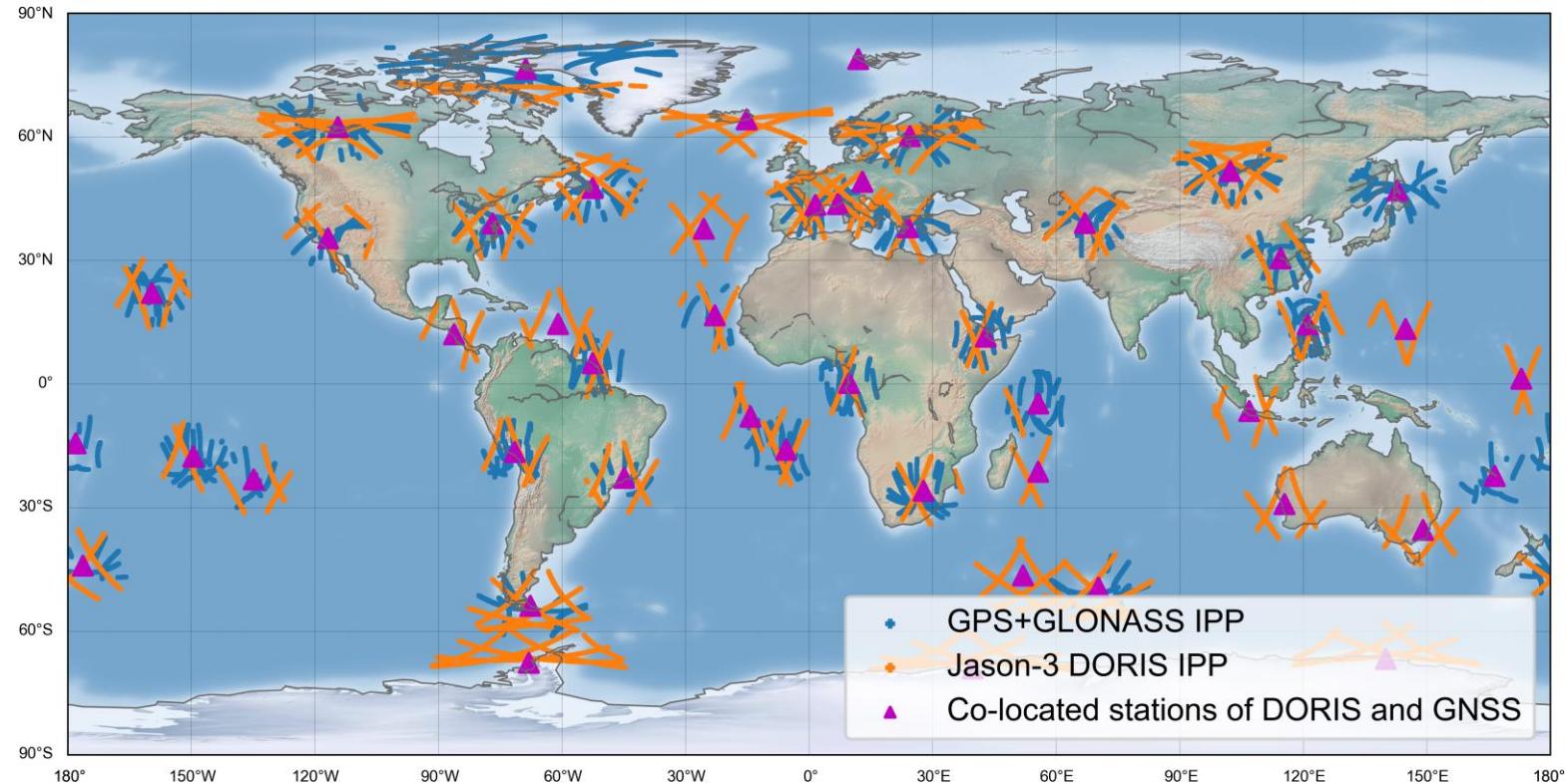
¹ IGS-SSR: IGS State Space Representation (SSR) Format

² RTCM-SSR: RTCM State Space Representation (SSR) Format



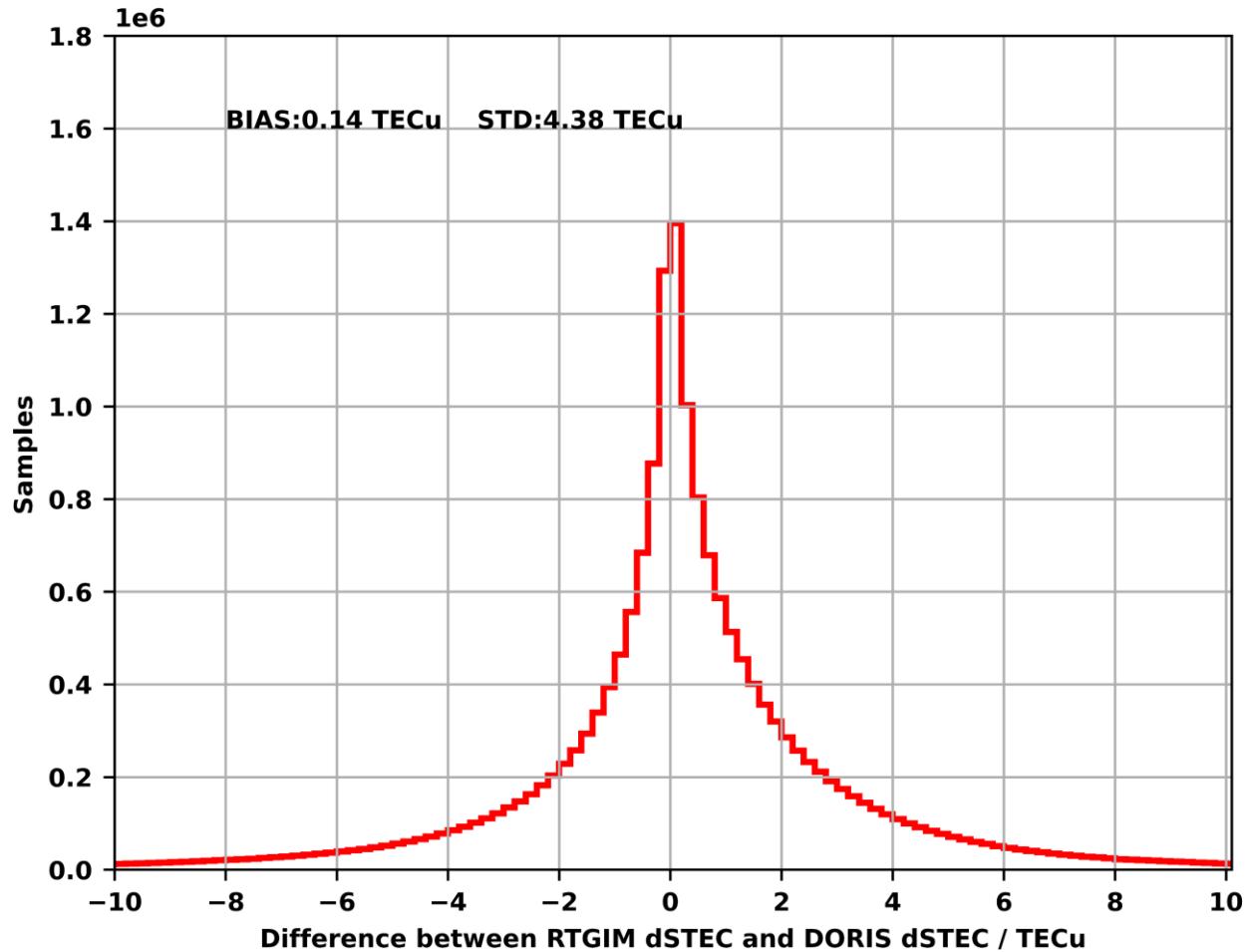
The selected 48 DORIS beacons and co-located GNSS stations

- ▶ NRT DORIS data from Jason-3 altimetry used for DORIS dSTEC analysis
- ▶ GPS and GLONASS observations of the IGS network used for GNSS dSTEC analysis





Consistency b.w.t. RT-GIM derived and DORIS observed dSTECs

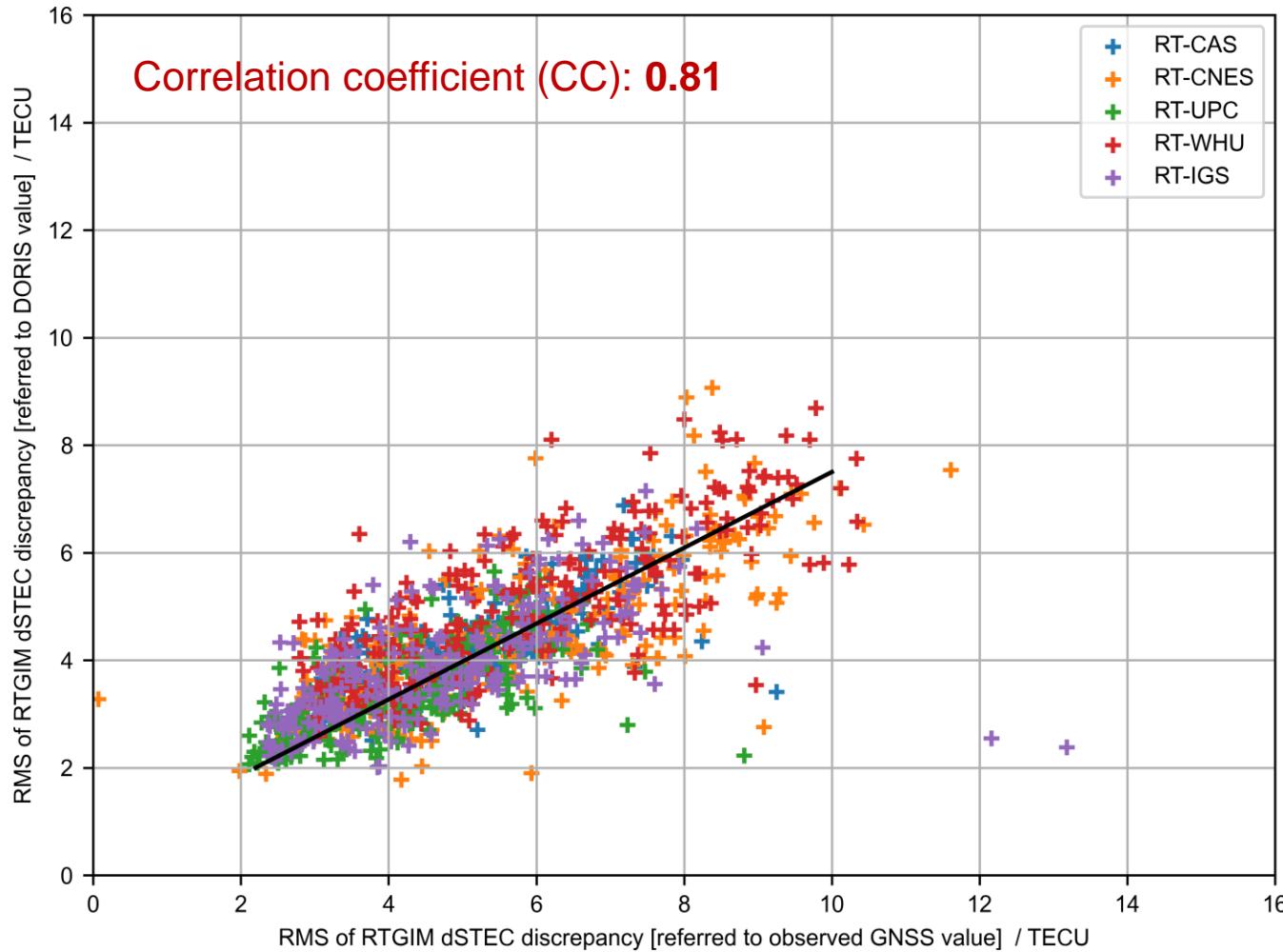


- ▶ more than 18,000,000 DORIS dSTEC observables used for the analysis.
- ▶ around 77.1% of the dSTEC differences is below +/- 3.0 TECu.
- ▶ no systematic bias found b.w.t. Jason-3 DORIS dSTEC and RT-GIM derived dSTEC.

Histogram of differences b.w.t. RT-GIM derived and DORIS observed dSTECs during DOY 001–110, 2022



Consistency b.w.t. DORIS (Jason-3) and GNSS (G/R) dSTEC assessments



RMS of RT-GIM dSTEC discrepancy referring to DORIS data versus that referring to GPS/GLONASS data during DOY 001-110, 2022.



RT GNSS data for GIM combination – CAS OPERATIONAL computation line

- ▶ Input streams: SSRC00CAS1, SSRC00CNE1, IONO00UPC1 and IONO00WHU0
- ▶ RT-combination strategy: **RT-GNSS dSTEC** analysis
- ▶ Station network for RT-GIM weighting: 30 RT-GNSS stations, $G(L1/L2)+E(E1/E5a)+C(B1/B3)$
- ▶ Generated streams: **IONO01IGS0** (RTCM-SSR) + **IONO01IGS1** (IGS-SSR)

NRT DORIS data for GIM combination – CAS new computation line

- ▶ Input RT-GIMs: SSRC00CAS1, SSRC00CNE1, IONO00UPC1 and IONO00WHU0
- ▶ NRT-combination strategy: **DORIS-dSTEC** analysis
- ▶ Station network for RT-GIM weighting: selected **48 DORIS** beacons
- ▶ Generated NRT combined GIM: IONEX files



Experimental NRT-GIM combination using Jason-3 NRT DORIS Data

- ▶ Input RT-GIMs: SSRC00CAS1, SSRC00CNE1, IONO00UPC1 and IONO00WHU0
- ▶ Input DORIS data: [Jason-3 NRT DORIS observation data \(ONE satellite\)](#)

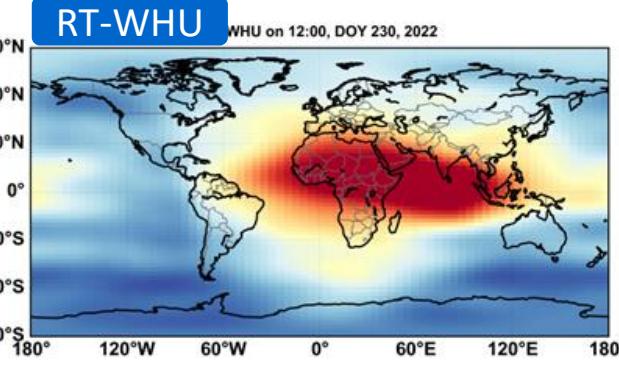
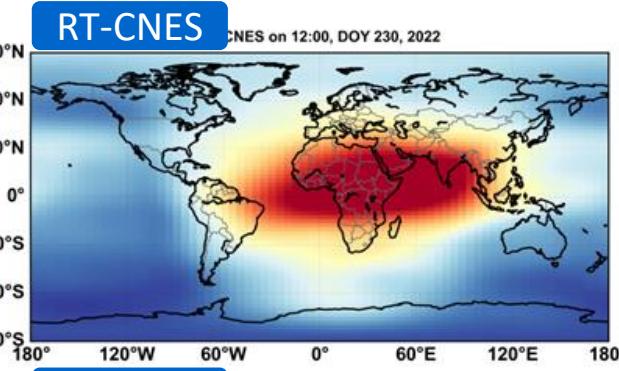
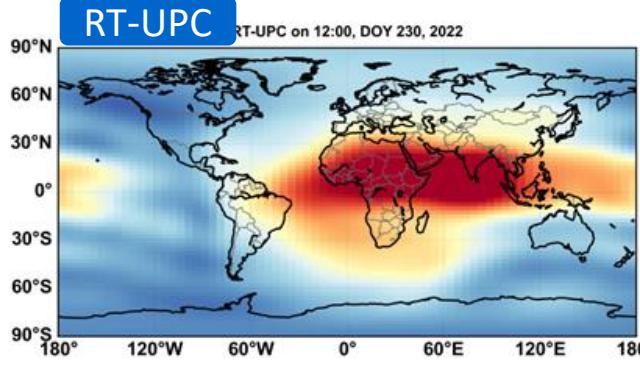
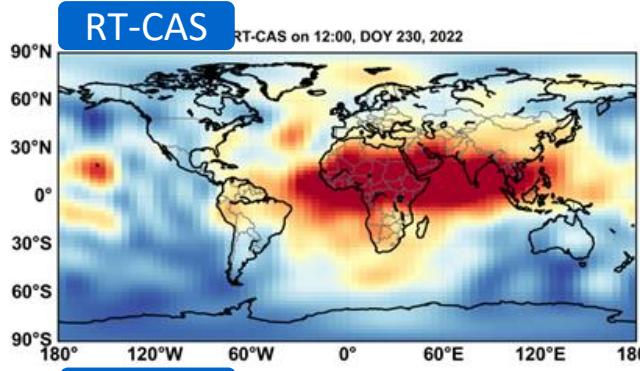
GNSS and DORIS dSTEC derived weights of different RT-GIMs

RT-GIMs	GNSS-dSTEC derived weights	DORIS-dSTEC derived weights
RT-CAS	0.29	0.24
RT-CNES	0.19	0.21
RT-UPC	0.35	0.35
RT-WHU	0.17	0.20

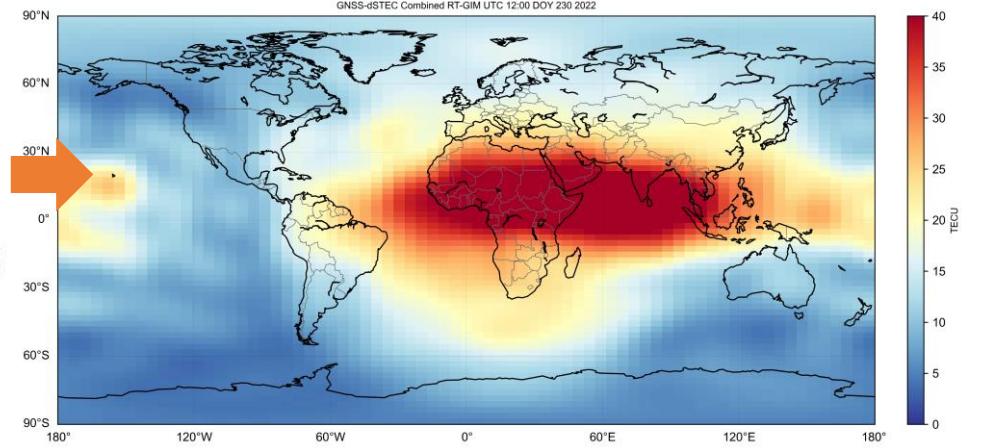
DOYs 001-270, 2022



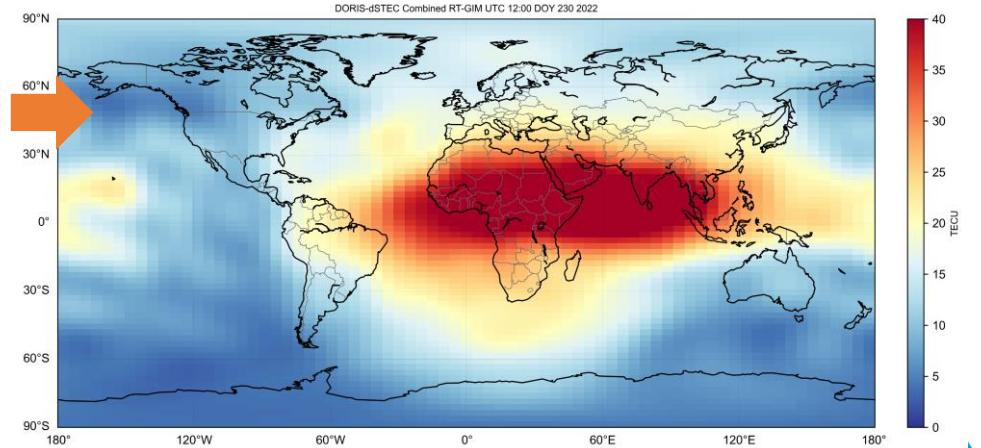
Experimental NRT-GIM combination using Jason-3 NRT DORIS Data



GNSS-dSTEC combined GIM

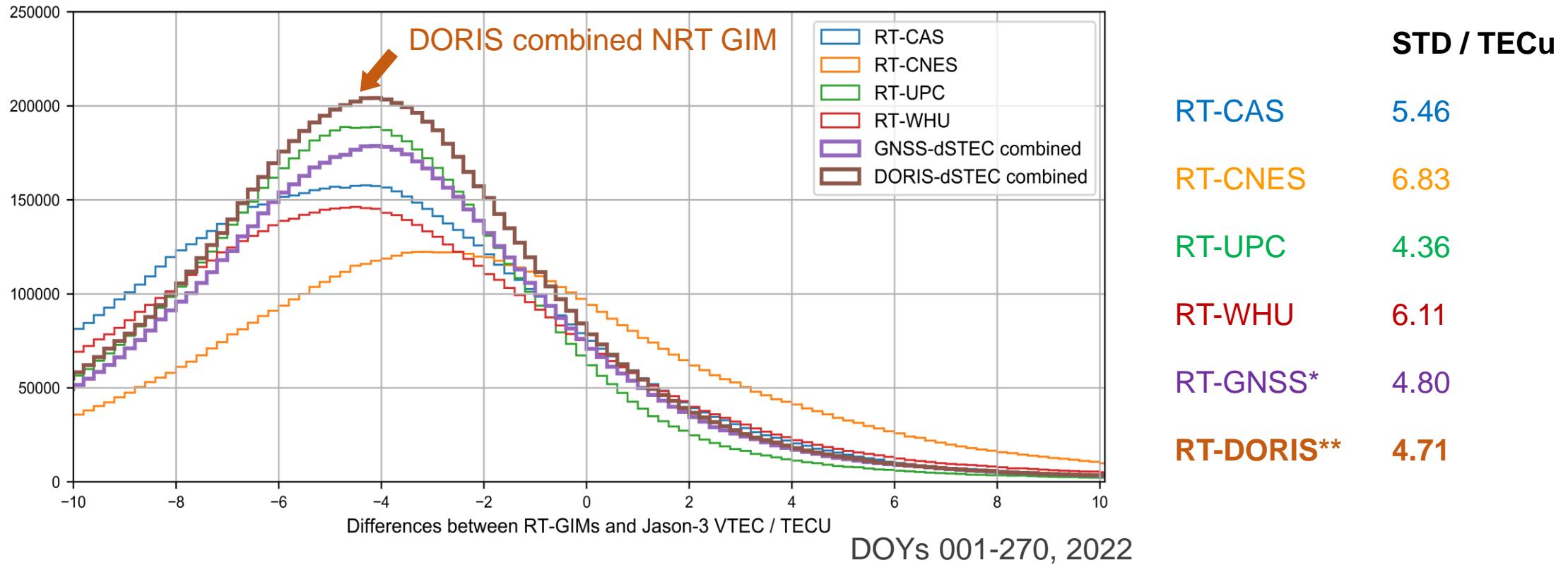


DORIS-dSTEC combined GIM





Experimental NRT-GIM combination using Jason-3 NRT DORIS Data



* RT-GNSS: GNSS-dSTEC combined RT-GIM

** RT-DORIS: DORIS-dSTEC combined RT-GIM



- ▶ The concept of **DORIS dSTEC assessment** is proposed, which is the extension of the existing GNSS dSTEC validation method.
- ▶ **No systematical bias is found** between RT-GIM derived dSTEC and DORIS observed dSTEC.
- ▶ The overall correlation coefficient is 0.81 for the validation result using DORIS and GNSS dSTEC.
- ▶ DORIS dSTEC assessment can be used as an independent way to validate the quality of those ground GPS/GNSS generated ionospheric models.
- ▶ The NRT & rapid combined GIMs are routinely generated at CAS using DORIS data.
- ▶ We have one proposal within the IGS Ionosphere Working Group to **provide independent rapid and final IGS combined GIMs.**



For more details, please refer to our ASR DORIS special issue paper

Liu A., Wang N., Dettmering D., Li Z., Schmidt M., Liang W., Yuan H.: Using DORIS Data for Validating Real-Time GNSS Ionosphere Maps. Advances in Space Research, 10.1016/j.asr.2023.01.050, 2023*

Thanks for your attention

