



*International
DORIS
Service*



Report on DORIS Rinex processing with Jason-2

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Range Rate from DORIS Rinex and corrections to observed measurement

$$\begin{aligned} \text{rrate } (T^c) &= \lambda_1 (L_1 (T_i) - L_1 (T_{i-1})) / (T_i - T_{i-1}) \\ &= (D (T^c_i) - D (T^c_{i-1})) / \Delta T + c(\Delta t_r - \Delta t_e) / \Delta T + \\ &\quad \Delta_{\text{satellite USO frequency}} + \Delta_{\text{ionosphere}} + \Delta_{\text{relativity}} \end{aligned}$$

where

$D(T^c)$: distance between emitter (e) and receiver (r) 2GHz phase centers at TAI time (T^c), and includes Troposphere refraction. $c(\Delta t_r - \Delta t_e)$: satellite-beacon clock drift; Δt difference clock offsets between i and i-1 times

and

$\Delta_{\text{satellite USO frequency}}$: polynomial fit to offset estimates

$\Delta_{\text{ionosphere}}$: 1st order correction (Lemoine 2015)

$\Delta_{\text{relativity}}$: Periodic terms



DORIS Rinex range rate GEODYN processing (computed or theoretical measurement)

Rinex range rate :

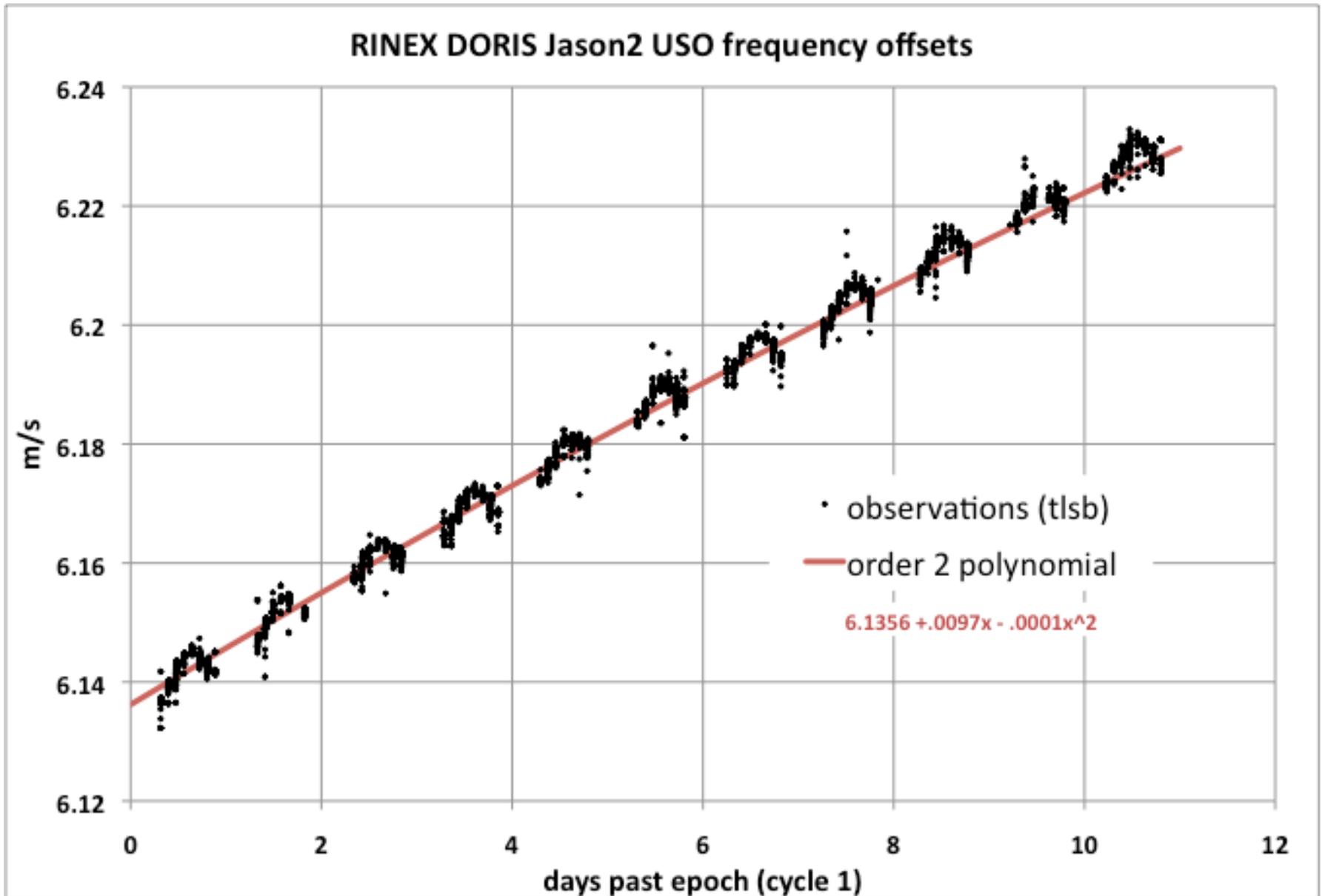
**range rate + USO frequency bias (per pass) +
 $\Delta_{\text{troposphere}}$ + $\Delta_{\text{phase center}}$**

where

**$\Delta_{\text{troposphere}}$: VMF1 (plus bias/pass)
 $\Delta_{\text{phase center}}$: update satellite antenna Z offset
and Starec station Up eccentricity
to ionosphere-free positions**

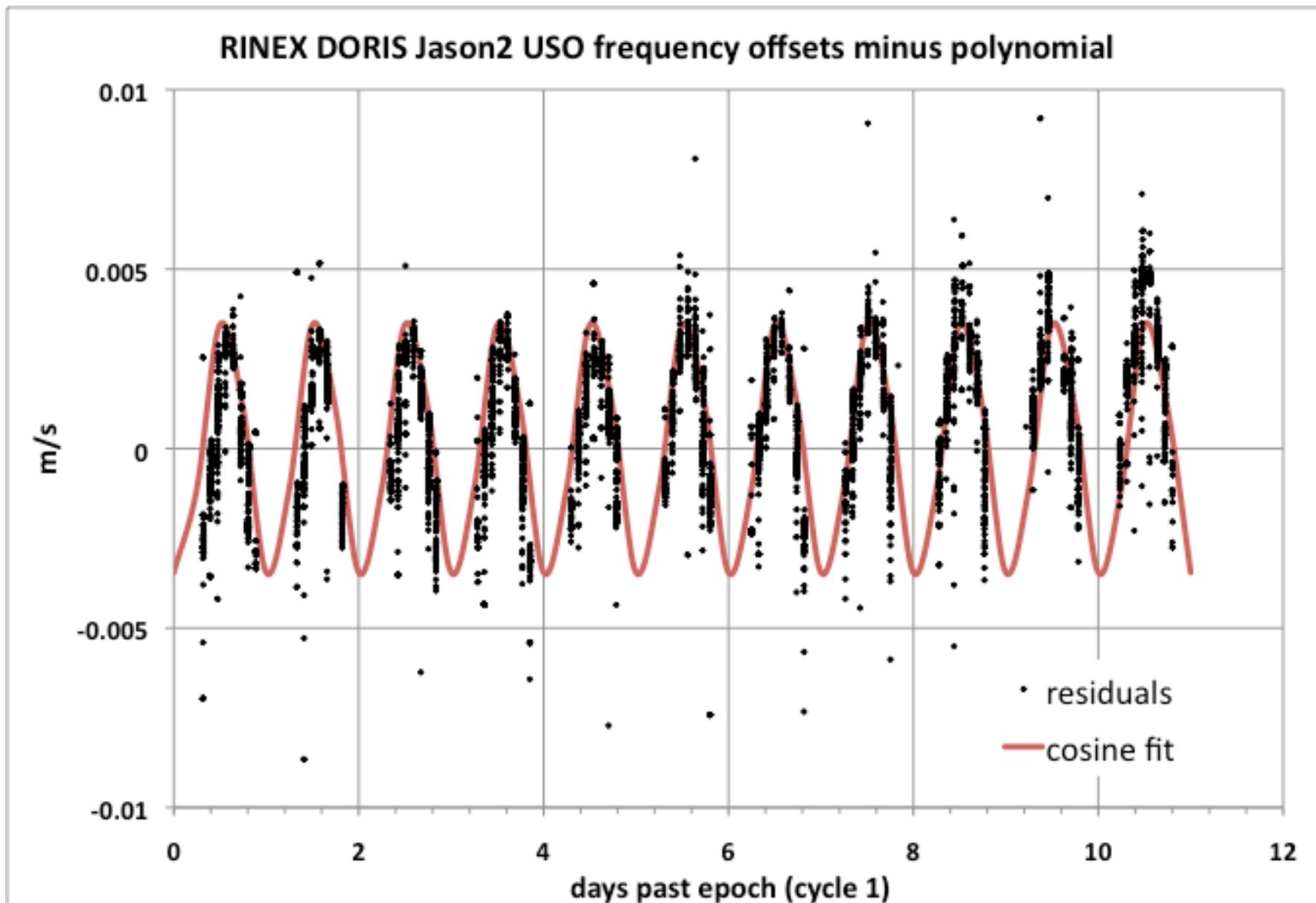


Δ satellite USO frequency : 2nd order polynomial fit





USO frequency correction residuals





USO frequency correction performance using external ephemeris

test (SLR/DORIS) 10-day (cycle 001)	DORIS points	DORIS (mm/s)	time bias (10^{-6} sec)
v2.2	187402	0.3686	-2.8
rinex; no correction	190605	0.3810	-1.0
rinex; linear correction	190565	0.3786	-0.9
rinex; 2 nd order polynomial	190573	0.3784	-1.0



Relativity correction to DORIS satellite clock

$$\Delta V_{REL} = \frac{1}{c} \left[U_r - U_e + \frac{V_r^2 - V_e^2}{2} \right]$$

(Lemoine et al.,
2015)

$$U = \frac{GM}{r} \left(1 - \left(\frac{a_e}{r} \right)^2 J_2 \frac{3 \sin^2(\varphi) - 1}{2} \right)$$

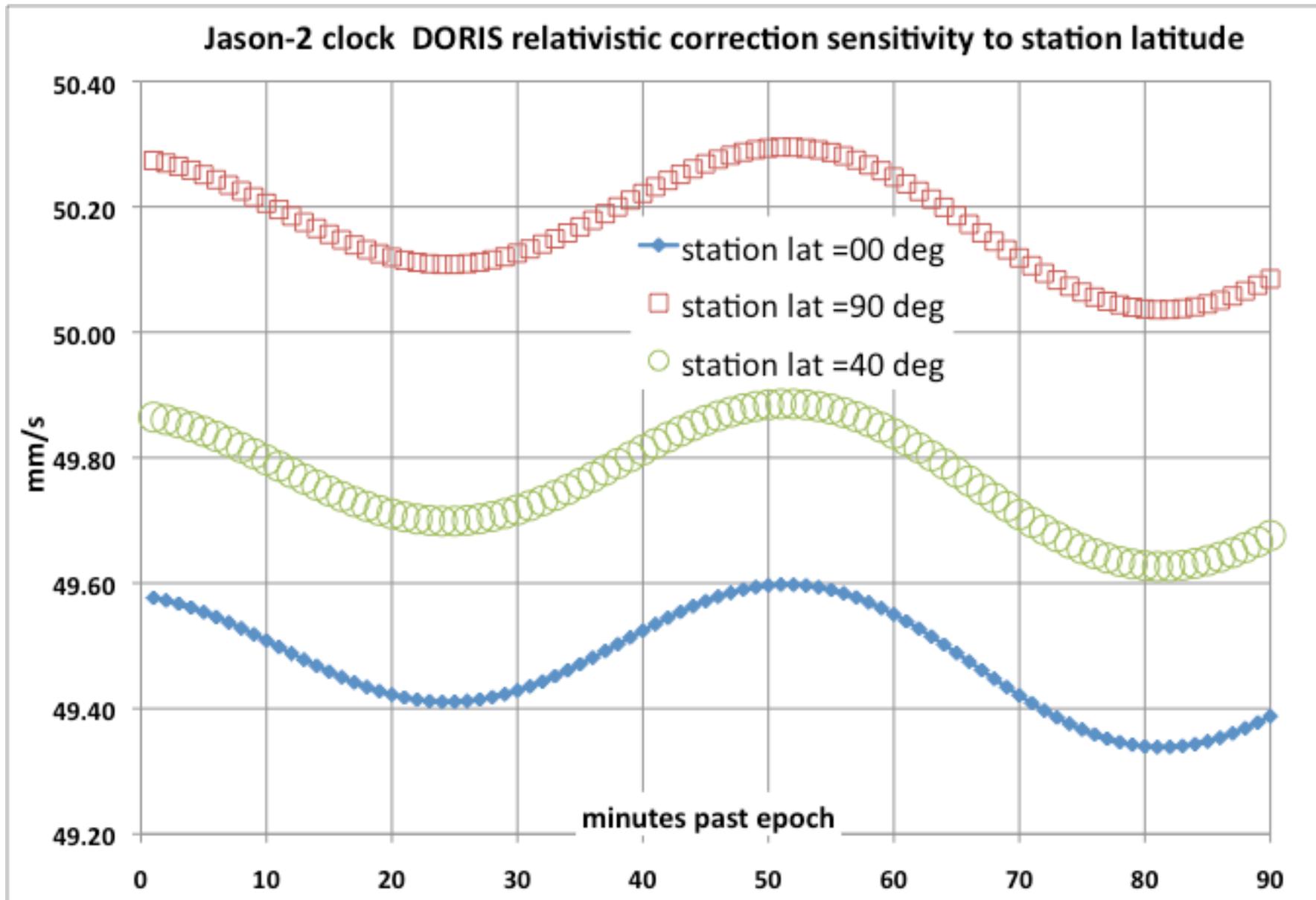
With $J_2 = 1.0826264 \cdot 10^{-3}$

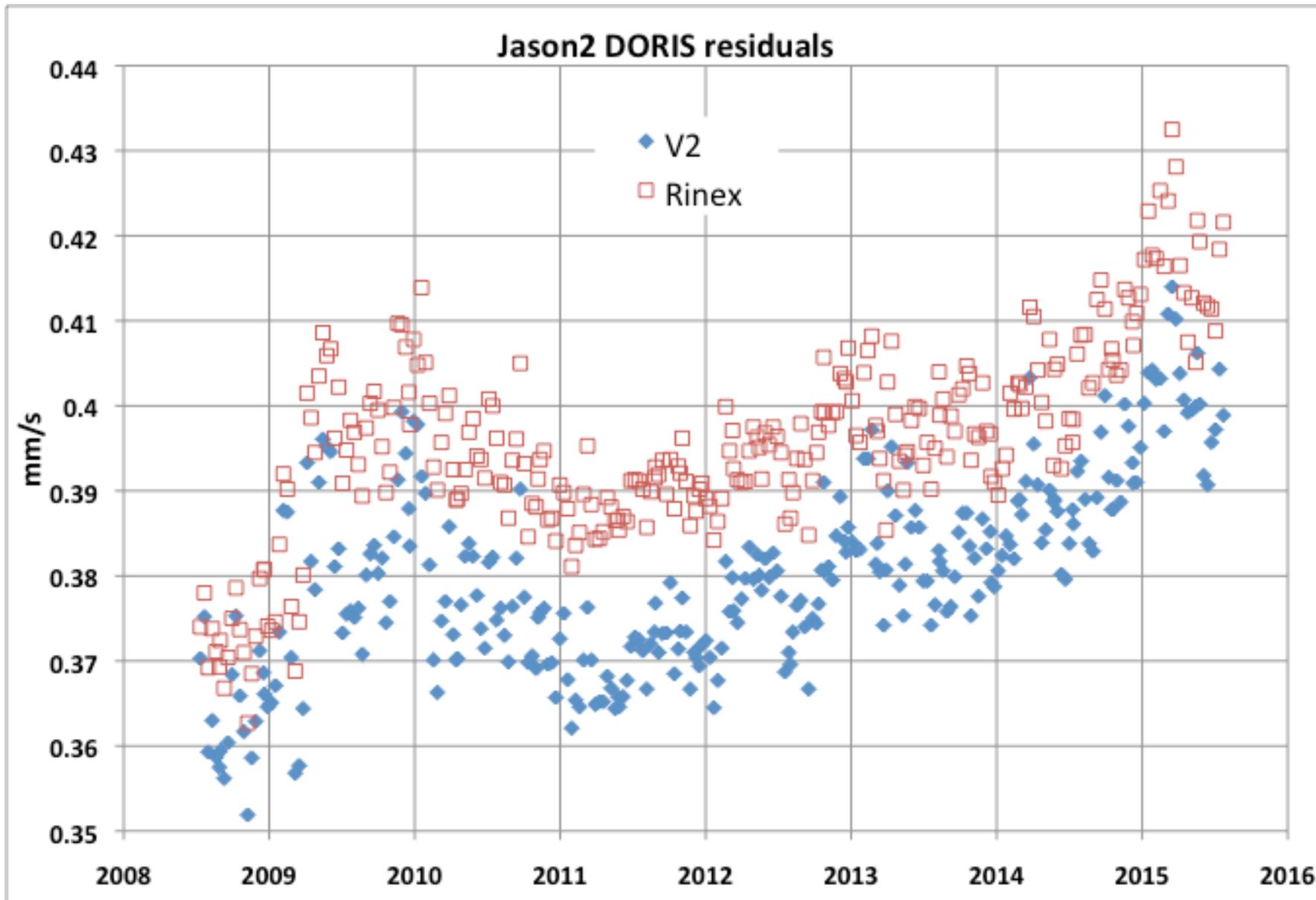
For correction to RINEX data:

- 1) use sp3 orbit data to compute U_r and V_r which vary in time.
- 2) assume a single station position to compute U_e and V_e which do not vary in time.
- 3) apply interpolated periodic terms after removing an estimated offset+rate from the total relativity correction.



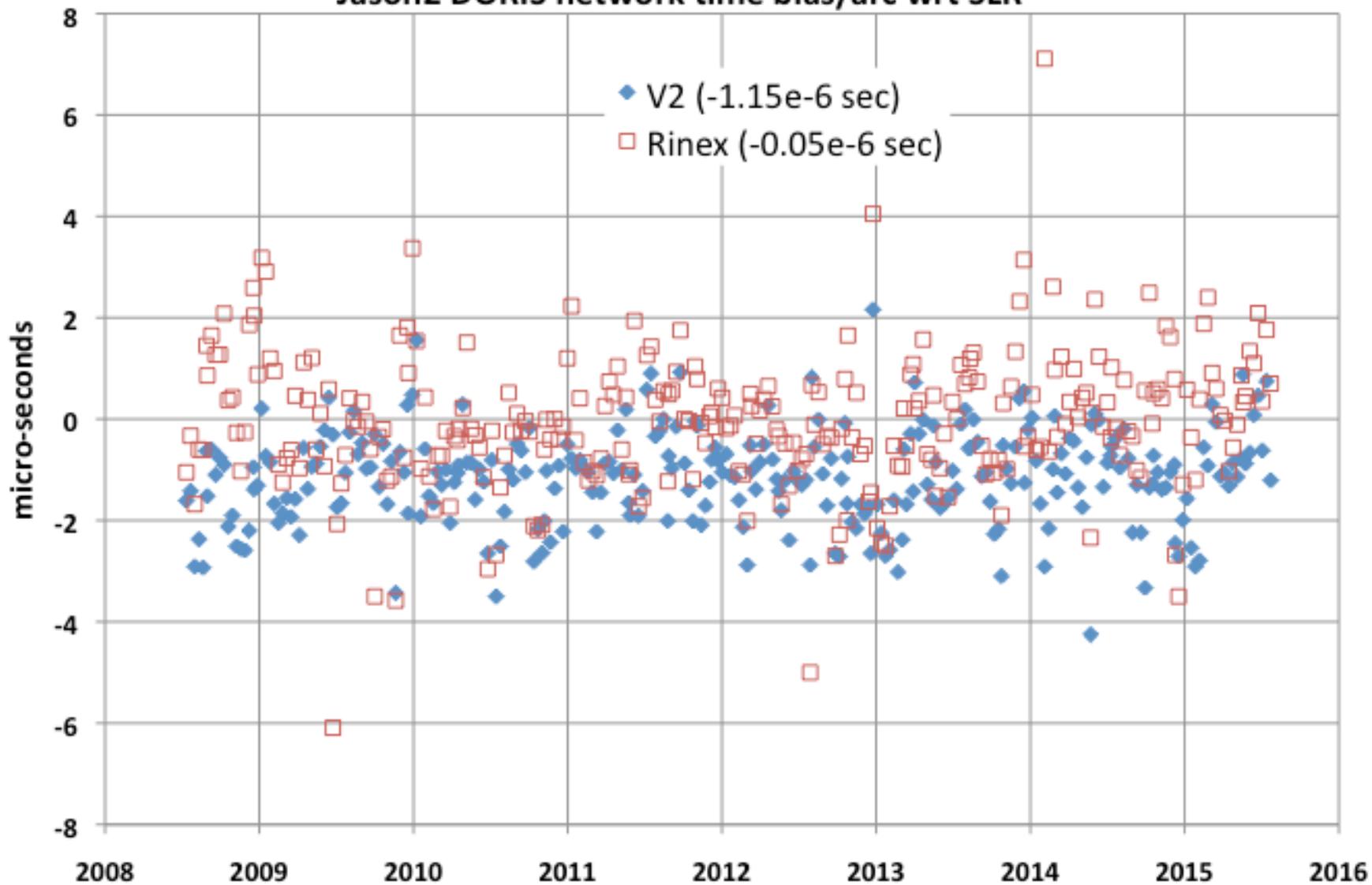
Station bias/pass will compensate for differences in Relativity offset/rate corrections

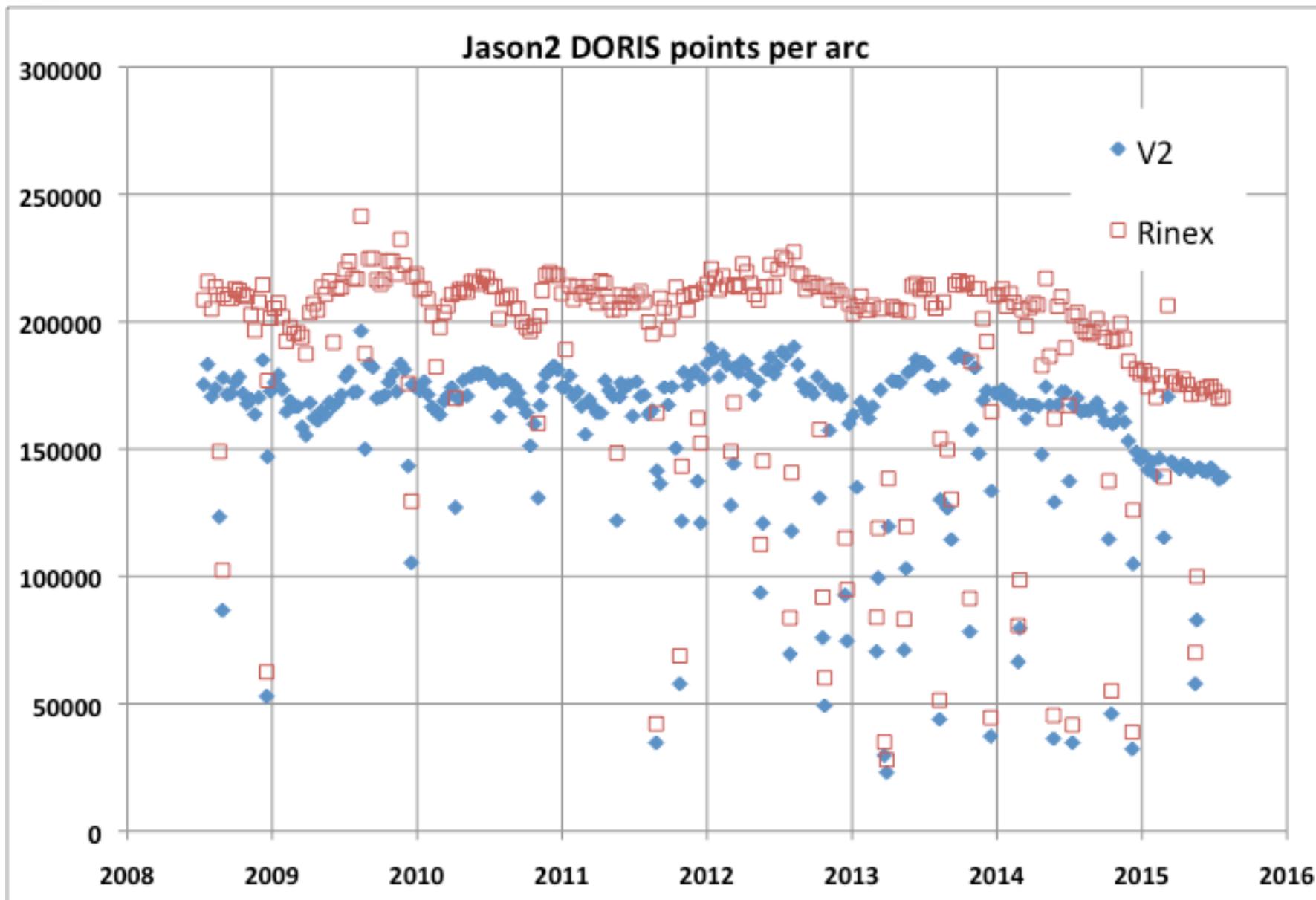


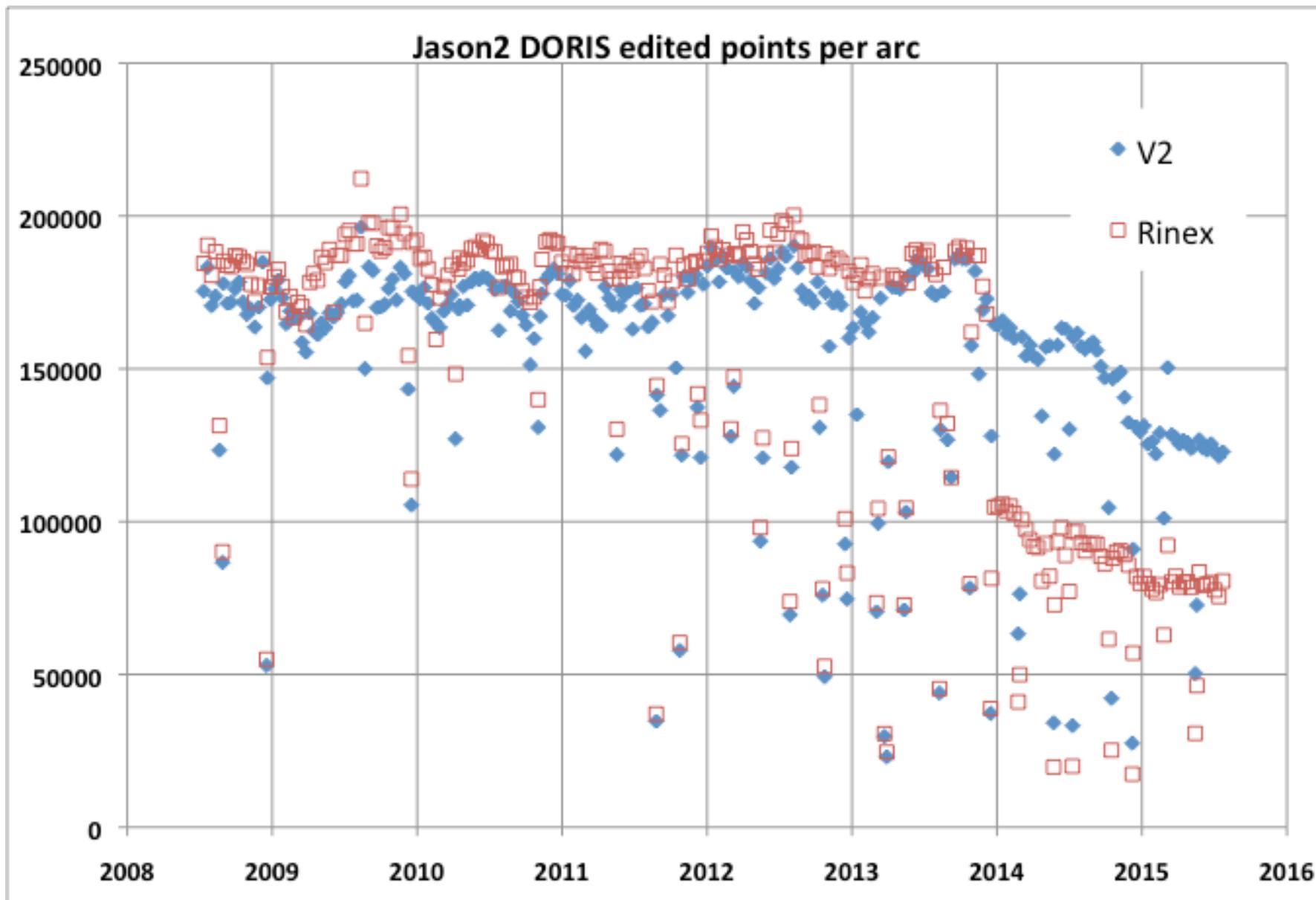


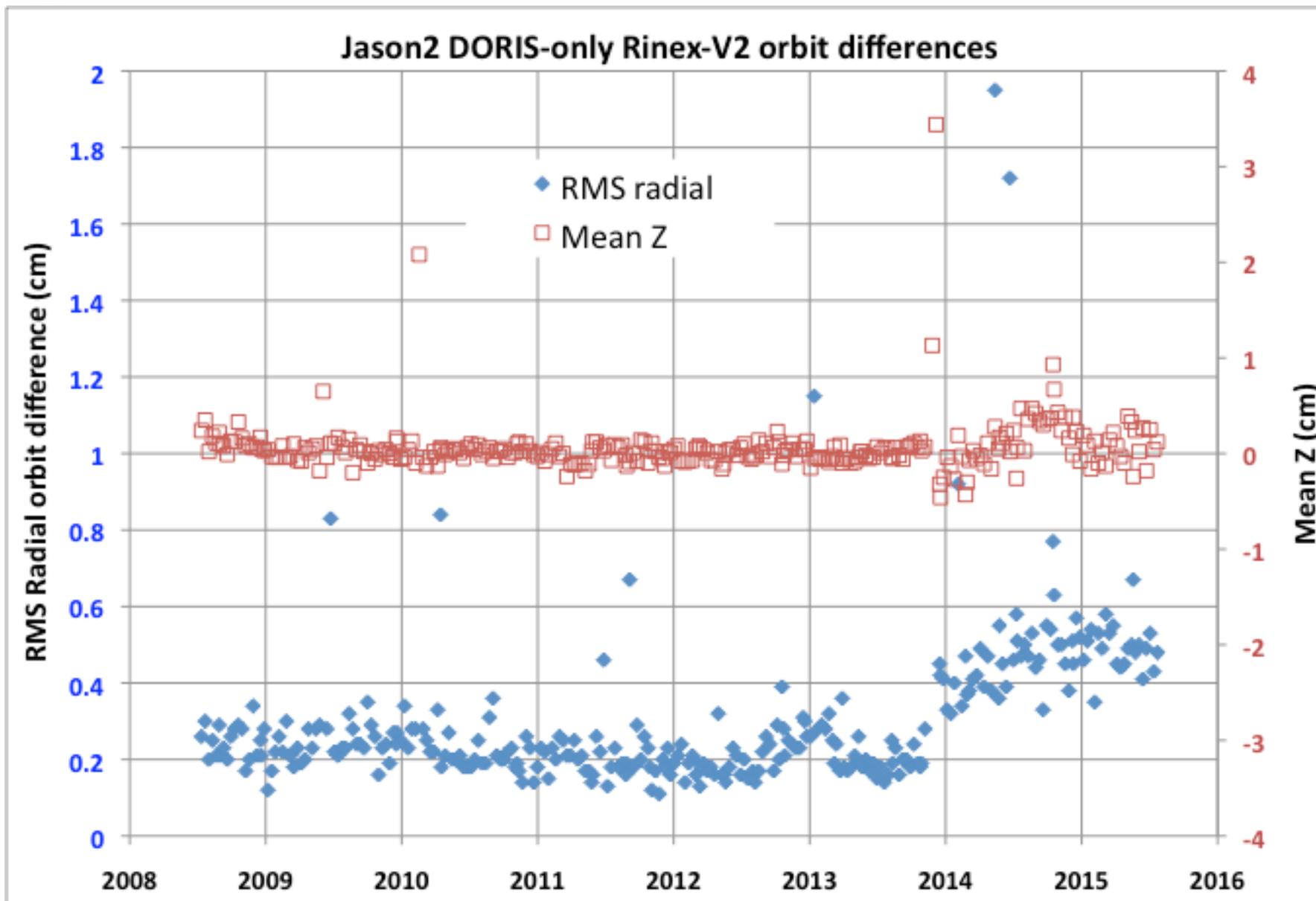


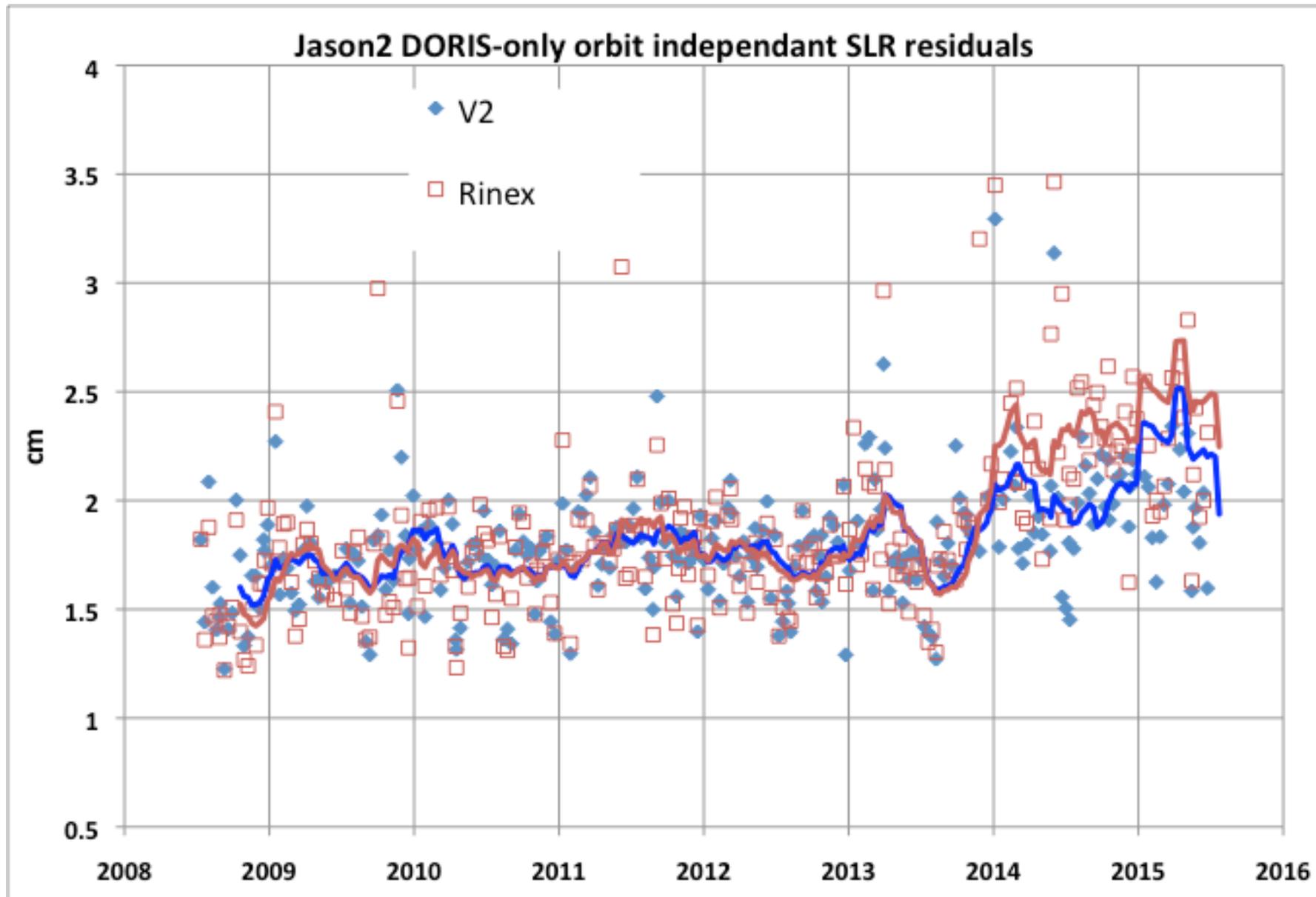
Jason2 DORIS network time bias/arc wrt SLR





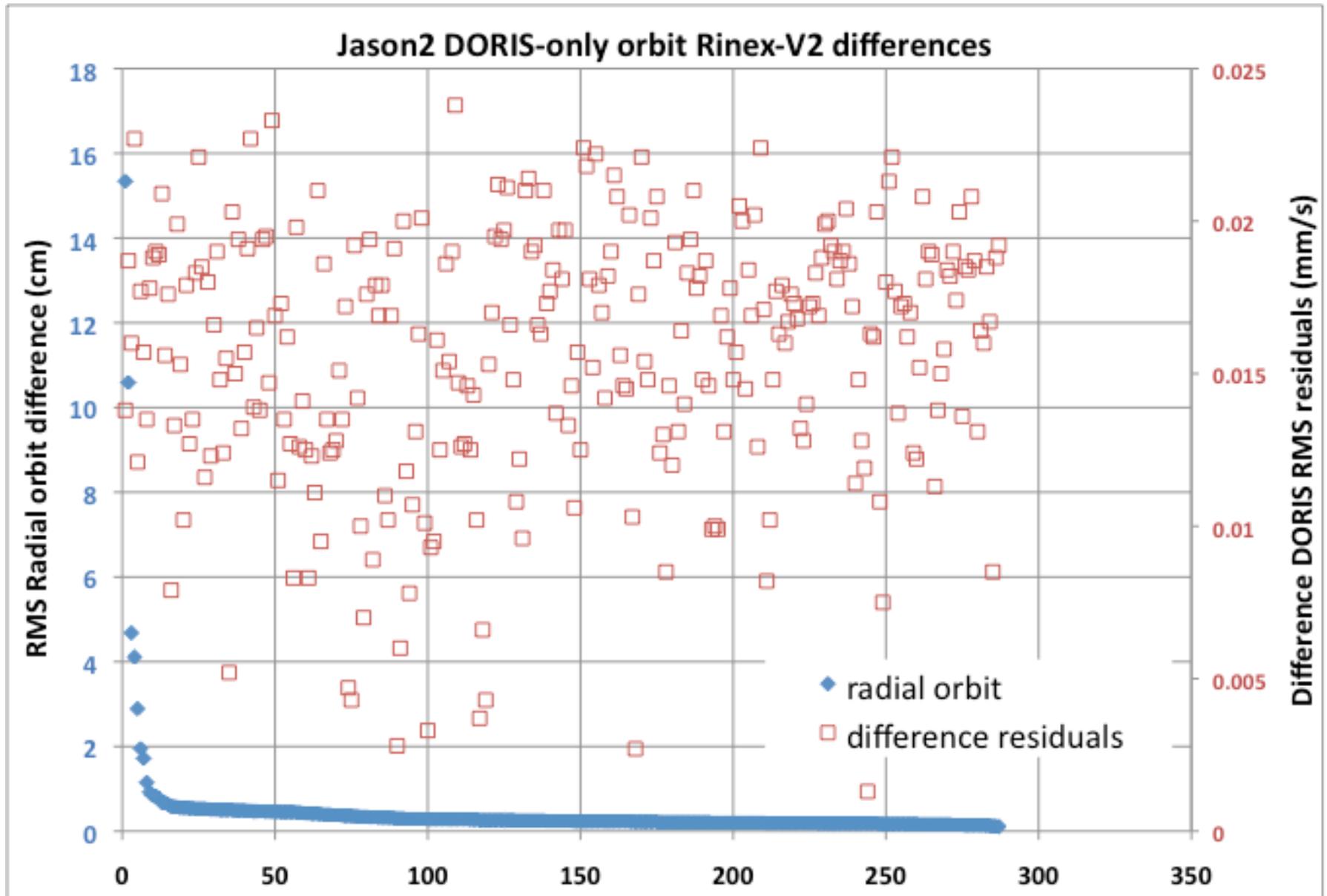






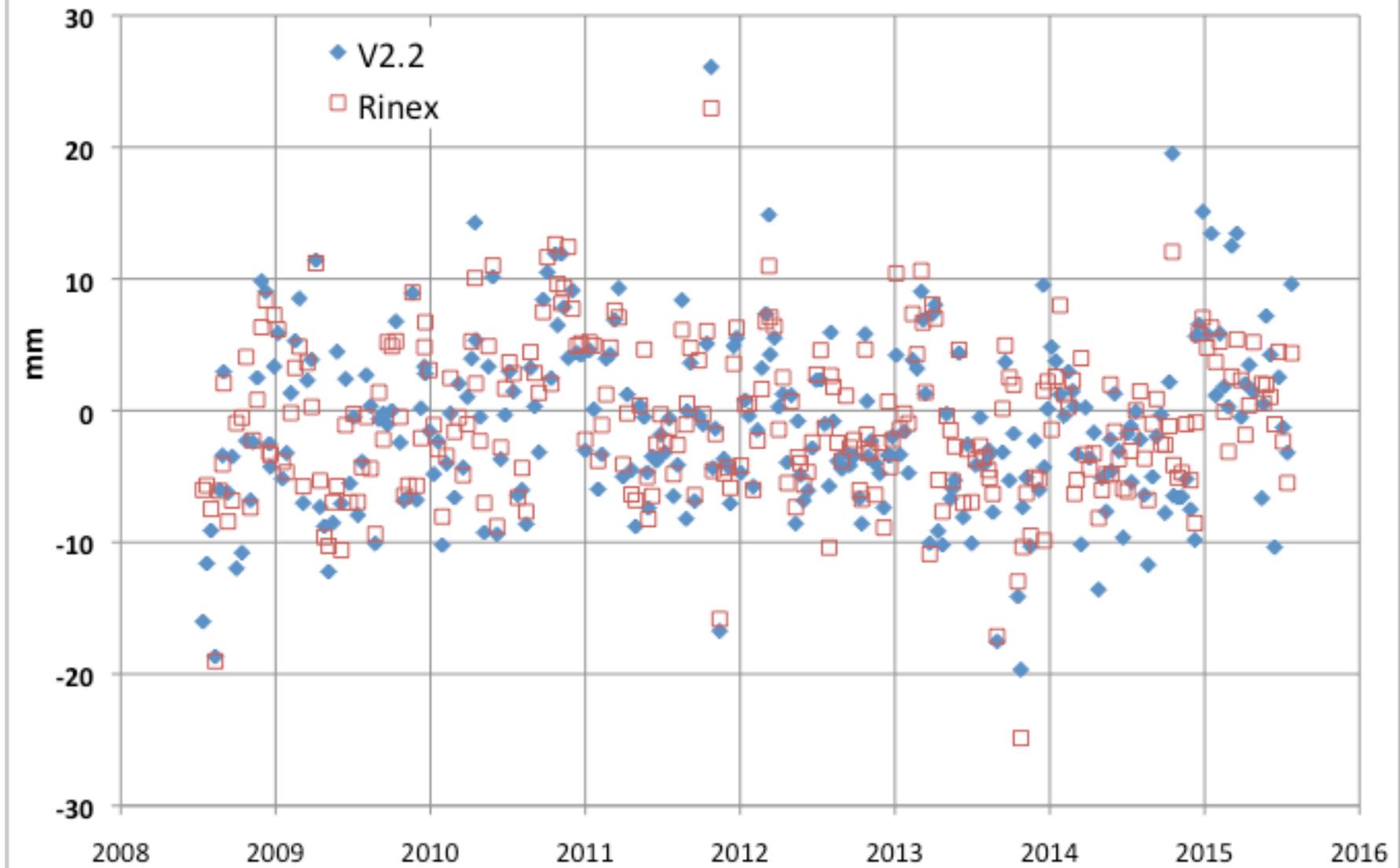


A few cases where Rinex DORIS converges to degraded orbits



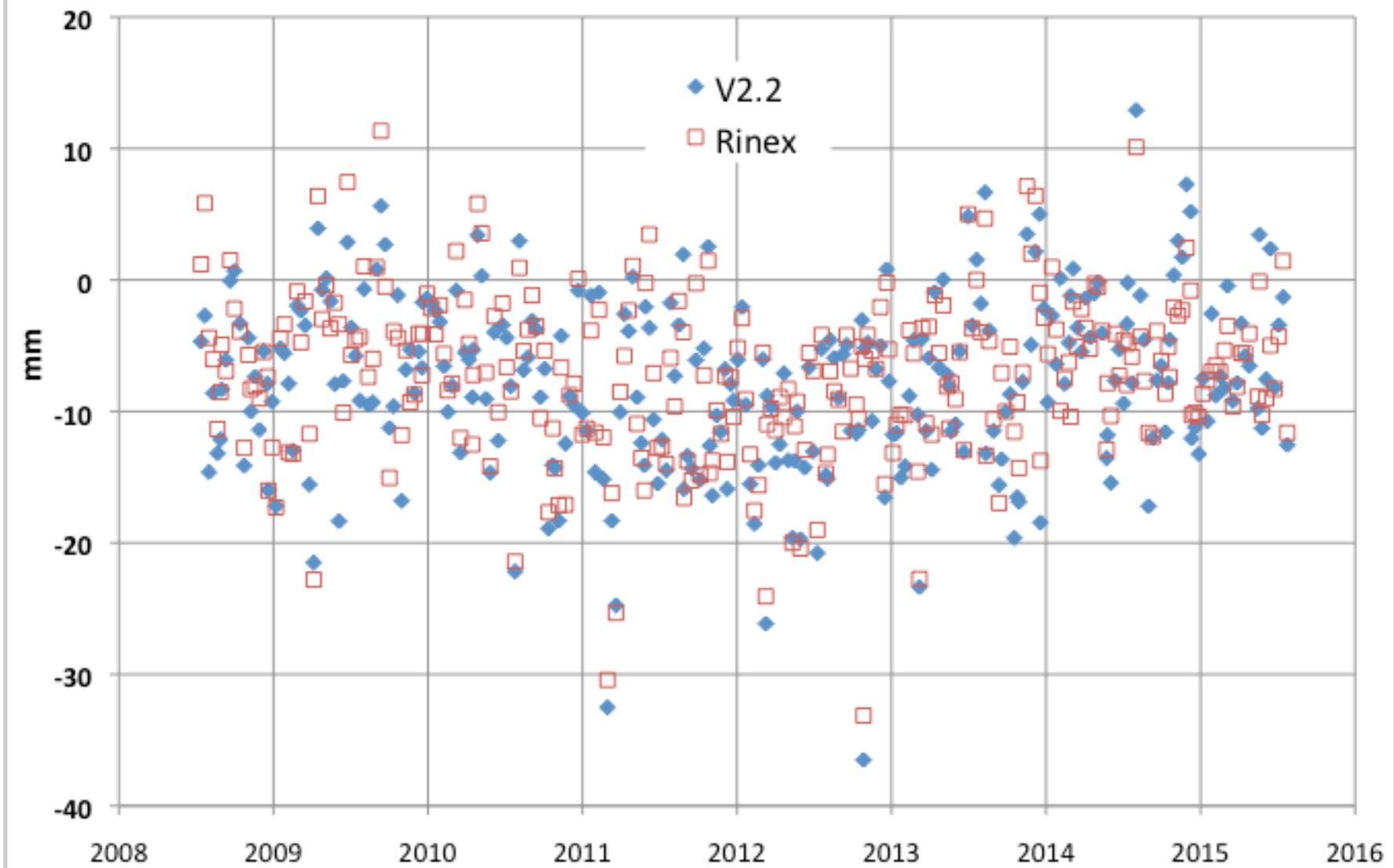


Jason2 DORIS 10-day station solutions compared to DPOD2008: Tx



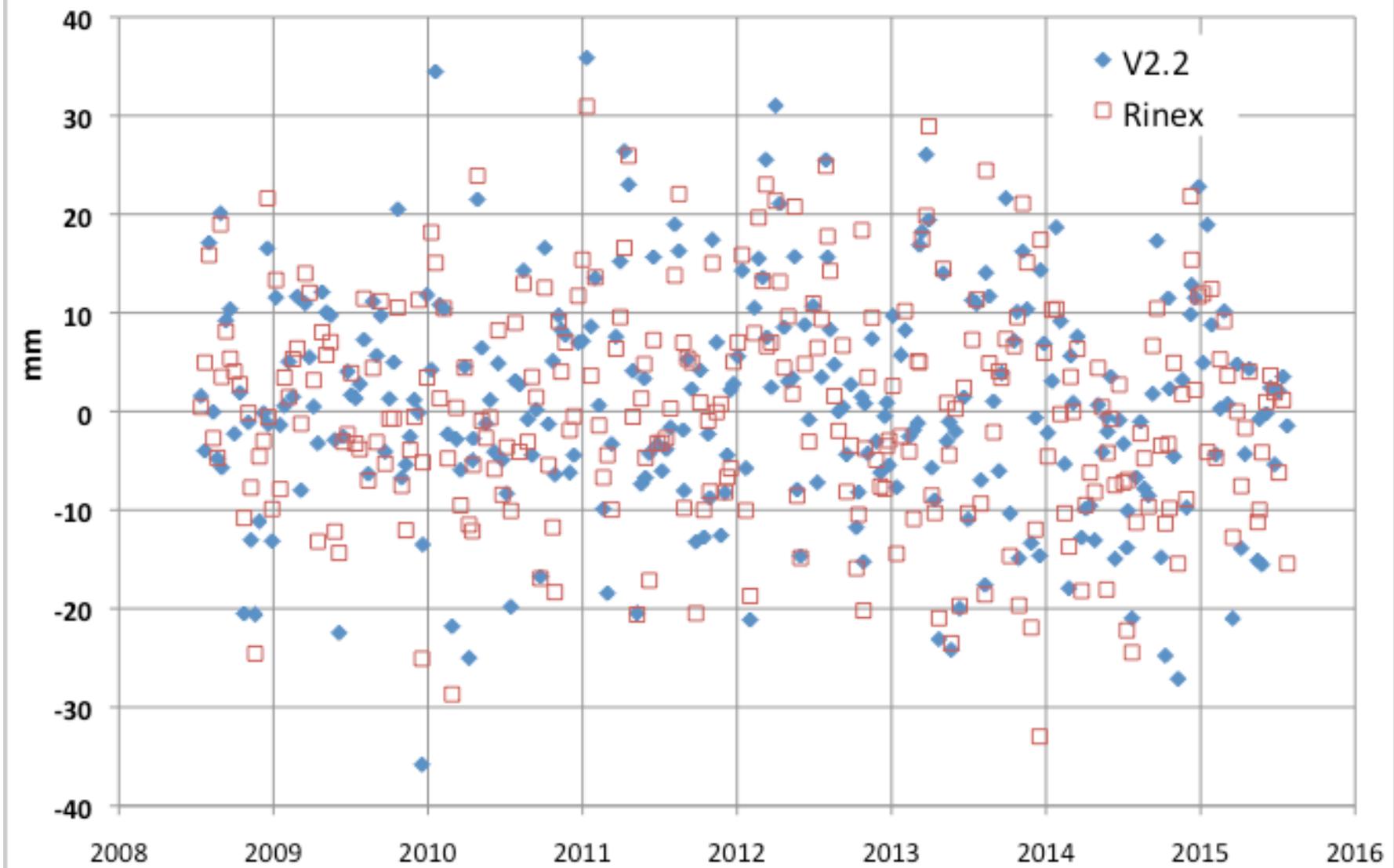


Jason2 DORIS 10-day station solutions compared to DPOD2008: Ty



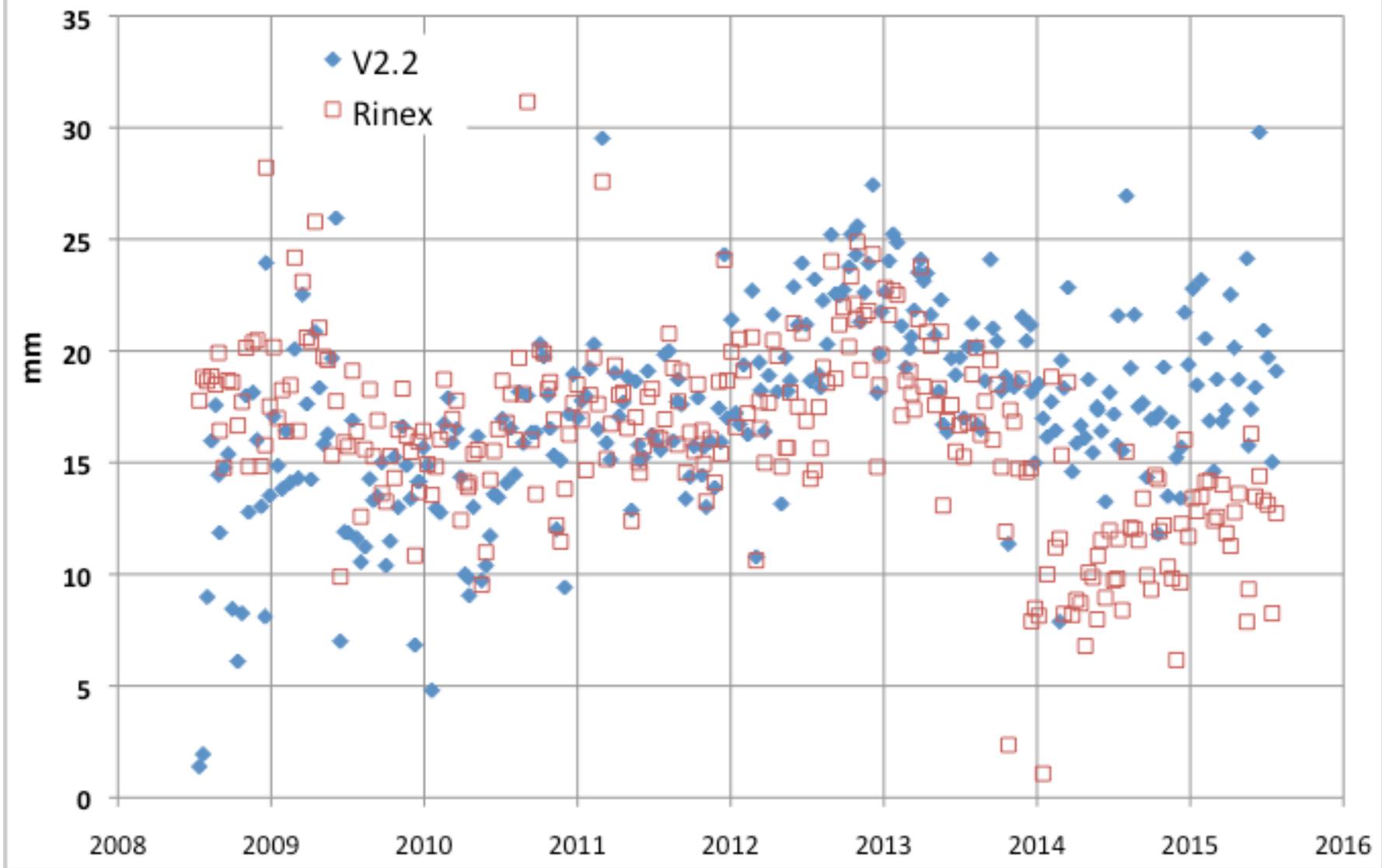


Jason2 DORIS 10-day station solutions compared to DPOD2008: Tz



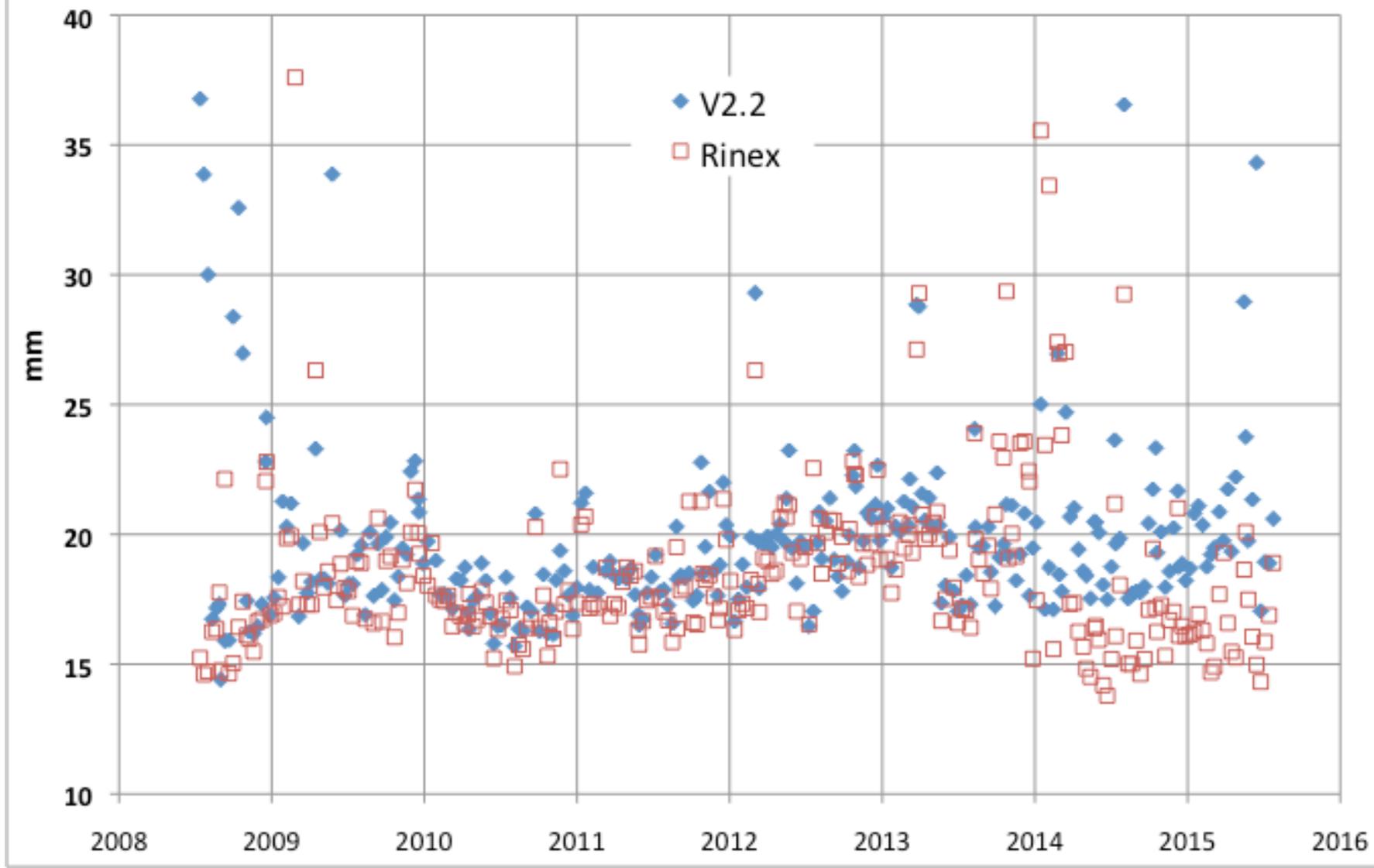


Jason2 DORIS 10-day station solutions compared to DPOD2008: [Scale](#)





Jason2 DORIS 10-day station solutions compared to DPOD2008: **WRMS**





Summary

- 1) Jason2 Rinex DORIS converted to range-rate and compared to V2.2 data processing over cycles 1-260.
- 2) Overall V2.2 /Rinex data POD processing compares as follows:

DORIS data	average points used	rms residuals mm/s	radial cm	cross-trk cm	along-trk cm
V2.2	152883	0.3803	---	---	---
Rinex	149142	0.3959	0.43	1.88	2.39

- 3) However there are two major problems:
 - 1) Isolated Rinex arcs can converge to degraded orbit solutions yet show normal DORIS residuals
 - 2) Rinex v10 data (from 2015) shows degraded POD

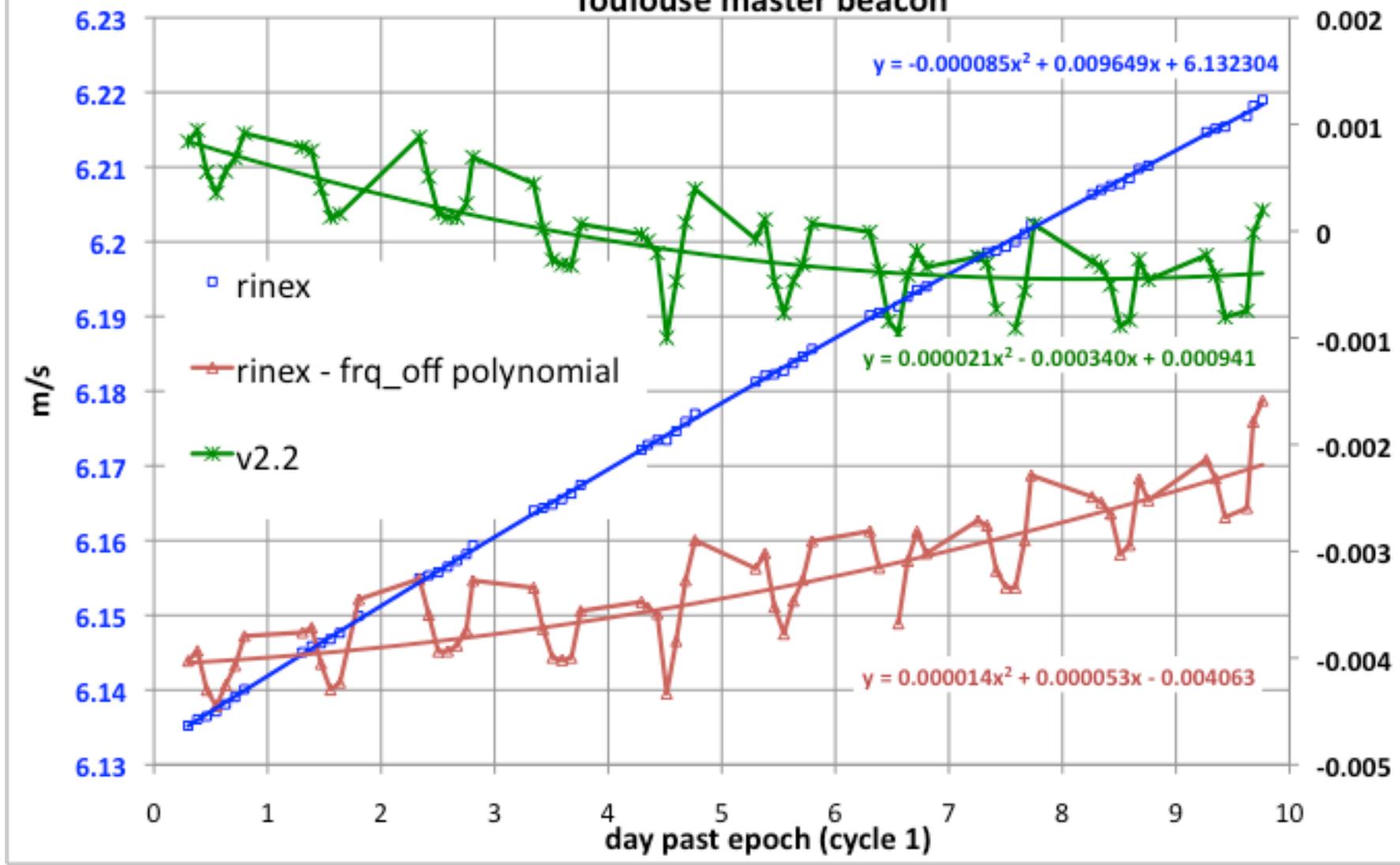


BACKUP





Jason-2 Rinex DORIS mbias / pass estimates over cycle 1: Toulouse master beacon





RINEX DORIS Jason2 USO frequency offsets

