

Current TRENDS in the DORIS SYSTEM

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acknowledgements to : Jean Pierre Granier, C. Jayles, Pierre Sengenes, Gilles Tavernier (CNES) , F. Rozo (COFRAMI), P. Souty (TAS)



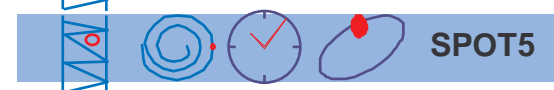
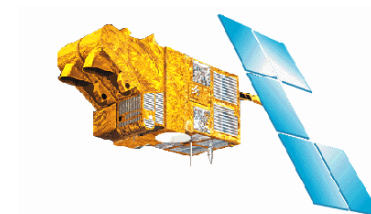
SUMMARY

- ➔ **Current/Planned DORIS Missions**
- ➔ **On board receivers**
 - 2G, 2GM, Cryosat receivers
 - future receivers
- ➔ **Network**
 - 3rd generation beacon
 - New Master Beacon
 - New Time Beacons?
- ➔ **EGSEs**
- ➔ **DORIS ground segment: SSALTO**









A Long Life System

90 91 92 93 94 95 96 97 98 99 2000 01 02 03 04 05 06 07 08 09 10



HY2, AQUARIUS (TBC)

-  POD
-  Models
-  IERS
-  Positioning
-  Navigation
-  Datation



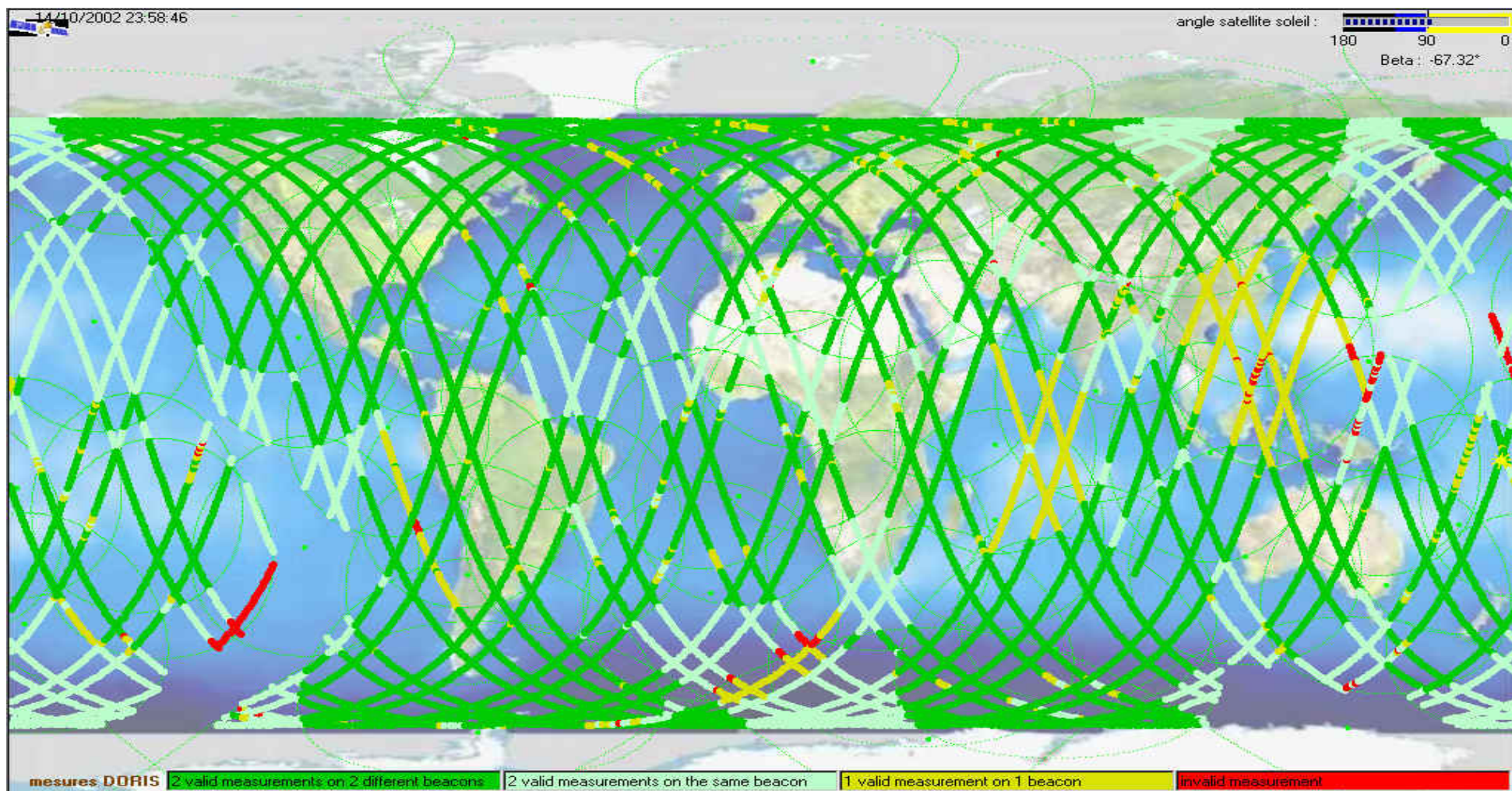
2G DORIS receiver: ENVISAT

- ➔ **Dual tracking ability : 2 beacons tracked simultaneously**
- ➔ **measurement resolution improved (1/4)**
- ➔ **New routine measurement mode : Autonomous mode**
 - **DIODE directives for beacon signal acquisition**
 - **daily uploads no longer needed**
- ➔ **Increased instrument operational robustness:**
 - **more autonomous onboard software**
 - ◆ wide range time correction
 - ◆ DIODE navigation function included in the flight sw and "lost in space" start
 - ◆ measurement mode autonomous management
 - **radiation-hardened processor,**
 - **EDAC and scrubbing task to prevent from mass memory upsets**
- ➔ **improved DIODE real time orbit accuracy**
 - **orbit estimation : \simeq 20-30 cm radial rms, 1 m 3-D rms position accuracy**
 - **TAI estimation : \simeq 1-2 μ sec rms**



Dual channel receivers orbit coverage

ex, Jason1 Oct 13-14 2002



At least 1 beacon : 93.4 % ; 2 different beacons : 62.9 %



2G miniaturised DORIS receiver

- ➔ 50 % size & mass reduction compared with ENVISAT 2G receiver
- ➔ Numerical processing
 - accurate phase measurements
- ➔ Cold start => from Switch On to routine w/o any ground commands
 - Thanks to TAI date transmitted by 3rdG beacons, and Time beacons
- ➔ Automatic update of onboard network description via Master Beacon broadcast

- ➔ Operated on board JASON1, SPOT5



CRYOSAT receiver

➔ New processor

- Sparc ERC 32
- improved arithmetic (improves quality of on-board processing)

➔ 2 redounded EEPROM banks to store the OBSW

- no more PROM
- OBSW maintenance improved

➔ New SoftWare

- Full SW upload w/o any mission interruption
- Provision of real time navigation in J2000 (SCAO use)
- Self-content raw measurements TM Packets
 - ◆ TAI dating ($1\mu\text{s}$ RMS) for raw measurements
 - ◆ on-board frequency estimation
 - ◆ time delays
- Improved RAIM and FDIR
 - ◆ deletion of IDLE and Incident modes
 - ◆ simplified operations



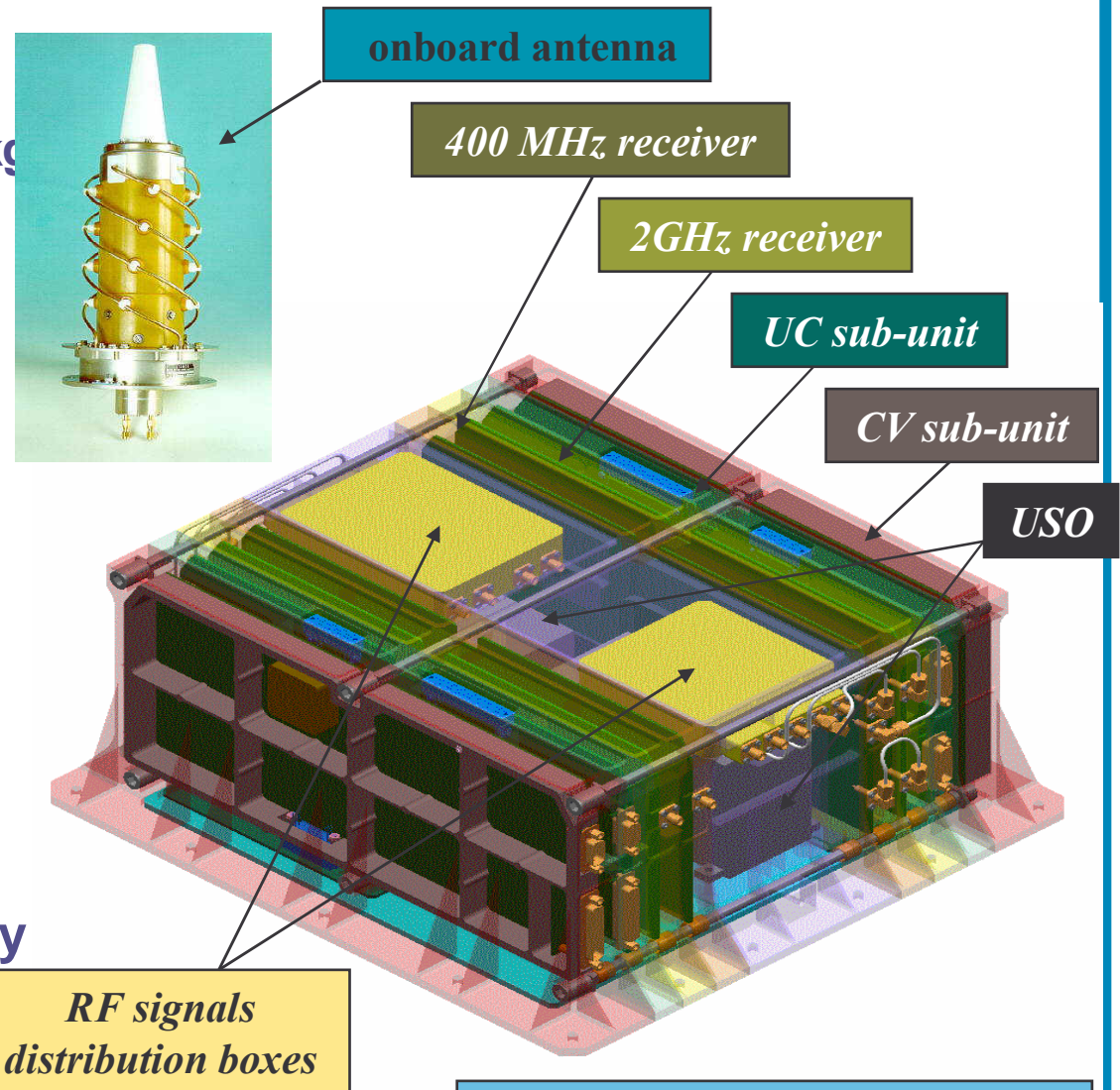
DGXX receivers

- ➔ At least 6 channels => capacity to track 6 beacons simultaneously
- ➔ New USO
 - increased stability
 - less sensitive to radiation
- ➔ Spectral analysis
 - beacon frequency search using FFT => shorter cold start (SCAO use)
 - spectral analysis mode maintained on one channel
 - ◆ new/unknown beacon (network, positioning)
 - ◆ safe mode
 - Jamming measurements performed simultaneously with main mission
- ➔ Satellite attitude taken into account on board (quaternions)
- ➔ 5 boxes (2GM, Cryosat) --> 1 box
 - simplified integration on the satellite
- ➔ Planed on JASON2



Doris DGxx instrument digest

- ➔ mass : BDR 16.5 kg - antenna 2 kg
- ➔ overall dimensions (mm)
 - BDR : 388 x 366 x 165
 - Antenna : ϕ 160 x 428
- ➔ power consumption : < 24 W
- ➔ TM rate : ~ 1 Kbits/sec
- ➔ internal redundancy
 - # 2 independent complete DORIS receivers in the same box
 - # Antenna RF signals are automatically switched to the active DORIS receiver
- ➔ provides 3 reference frequency outputs (10 MHz USO) for POSEIDON-3 altimeters & WSOA



BDR : Redundant DORIS Box



Beacons Network

- ➔ Antenna change
- ➔ Antenna support stability Improvement
- ➔ Antenna positioning improvement

- ➔ 3rd G beacon deployment



3G beacon : main new features

- Frequency shift : ± 50 kHz / 2GHz ; ± 10 kHz / 400 MHz
 - => network density may be increased
- Beacon message and synchro. word transmitted on both 400 MHz & 2 GHz signals with EDAC code on 2GHz
 - => improves datation accuracy
 - => improves data reception on board
- Transmission of current non ambiguous TAI date
 - => allows receivers cold start
- Improved monitoring of beacon operation status (USO Warm-up)
 - => avoid erroneous processing
- Restart mode
 - => beacon switched ON without any time set
 - => beacon switch Off detection ; avoid erroneous processing
- remote control capacity
- can be easily upgraded into Time or Master Beacon



A new Master Beacon

➔ Why ?

- Faster cold start of the receivers (SCAO users)
- robustness

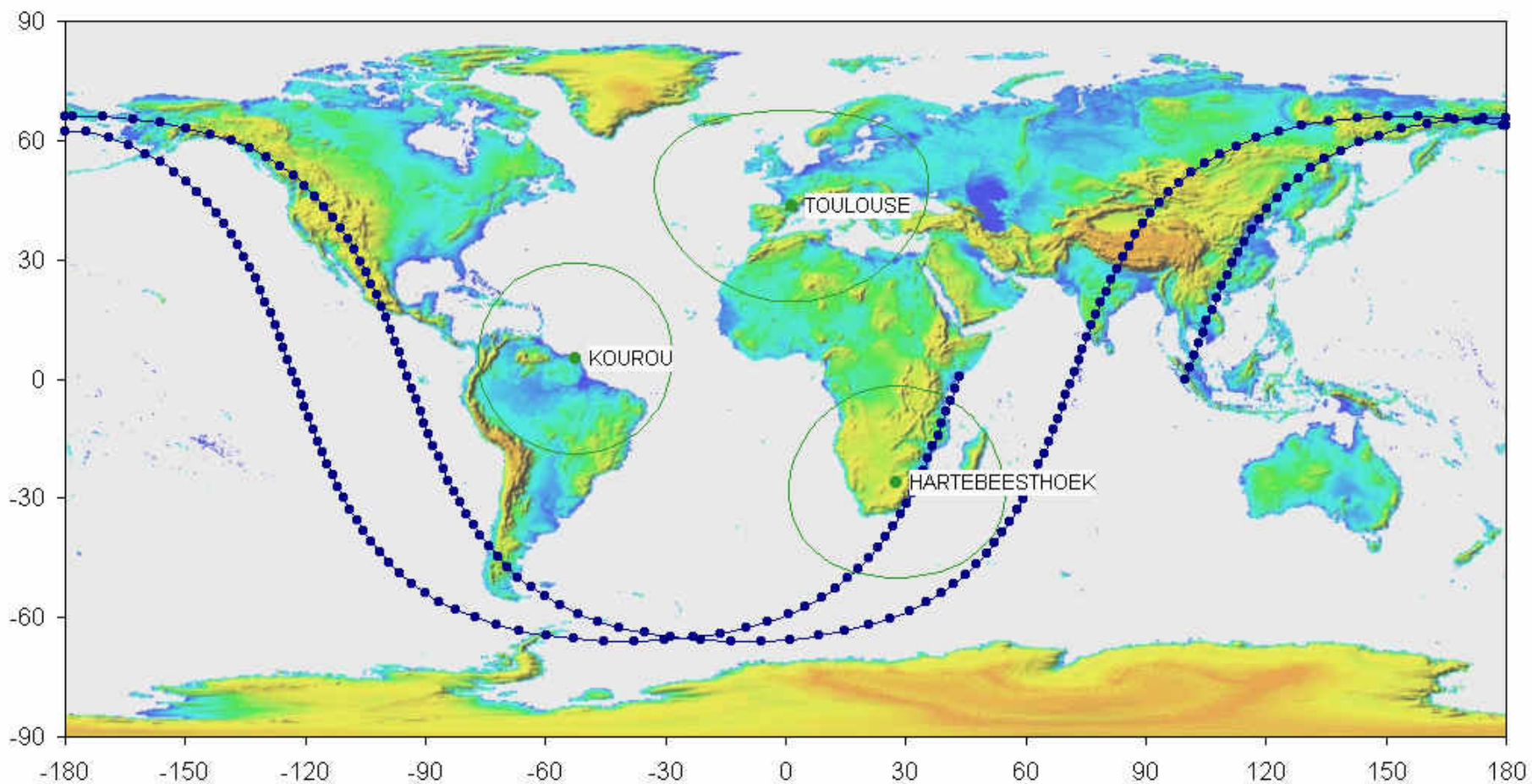
➔ Where ?

- Any reliable site (power and data link with DORIS Ground Segment)
- coverage improvement (no co-visibility with already existing MB)
 - ◆ HBK : installation planed before end of 2004



A new Master Beacon

Visibilités TOULOUSE, KOUROU, HARTEBEESTHOEK pour JASON (site mini 12 deg)
Avec 2 traces d'orbites consécutives, 1 minute entre 2 points



New Time Beacons (TBC)

➔ Why ?

- improved on-board USO monitoring (JASON1)
- faster cold start of the receivers (SCAO users)

➔ Where ?

- Any site assuming a reliable atomic clock is available
 - ◆ St Johnes site currently under study



New EGSEs

- ➔ simulation of RF signals as seen by the on board receiver in flight including beacon messages, beacon time scales, broadcast transmission
 - ground tests representativity improved
 - useful for system investigations

- ➔ Already successfully used for DORIS/CRYOSAT OBSW validation



SSALTO multi-missions orbitography and altimetry center



- ➔ Taking into account new missions
- ➔ System control
 - broadcast generation
 - monitoring tools
- ➔ Pre-processing improvements
 - datation, beacons time correction
 - data edition (centre frequency wrong measurements)
- ➔ POD Processing improvements
 - troposphere effect
 - USO frequency modelling currently under study
- ➔ SSALTO improved characteristics
 - modular conception allowing new instruments to be easily integrated
 - centralised data archiving
 - includes public results interface and distribution
 - beacons positioning is included in operational processing



Conclusion

- ➔ **DORIS System evolutions**
 - to be closer to users needs
 - to increase reliability
 - to reduce cost

- ➔ **Any suggestions ?**

