

Preprocessing of Doris phase data for Doppler solutions and low elevation measurements

F. Mercier, J. Moyard, H. Ait Lakbir

IDS Workshop Munich 2019

Objective

Improvement of the preprocessing for low elevation measurements (5 degrees)

Remark : an elimination based on Doppler residuals is probably not a good approach because it interrupts the continuity of the phase
(like having 2 ambiguities to adjust instead of 1)

The measurement elimination must produce the best possible phase continuity

avoid unnecessary interruptions
(for example a too conservative elimination based on Doppler measurement noise)

→ improve the processing for high elevation measurements
currently eliminated with the flag ' low Doppler measurements'

reconstruct if possible some cycle slips occurring at high elevation
(observed on Jason 2, see '*Jason-2 DORIS phase measurement processing, JASR 2010*)

Examples and formulation

Example : mean frequency estimation

estimation of the mean frequency for a pass, taking into account the phase noise only
 (unmodelled USO error : implies more complex correlations between the measurements)

phase variations over 10 s

phase measurement
noise σ_x

$$y_{k+1} = x_{k+1} - x_k$$

Mean frequency estimation over a pass, with Doris standard processing (using phase variations) :

$$f = \frac{1}{n} \sum_1^n y_k$$

Example : mean frequency estimation

estimation of the mean frequency for a pass, taking into account the phase noise only
 (unmodelled USO error : implies more complex correlations between the measurements)

phase variations over 10 s

phase measurement
noise σ_x

$$y_{k+1} = x_{k+1} - x_k$$

Mean frequency estimation over a pass, with Doris standard processing (using phase variations) :

$$f = \frac{1}{n} \sum_1^n y_k = \frac{x_n - x_0}{n}$$

$$\text{error or } f : \frac{\sqrt{2}}{n} \sigma_x$$

➡ Effect of the elimination of one y_k measurement ?

Example : mean frequency estimation, Doppler measurement elimination

$$f = \frac{1}{n} \sum_1^n y_k = \frac{x_n - x_0}{n}$$

$$\text{error on } f : \frac{\sqrt{2}}{n} \sigma_x$$

If a Doppler measurement is eliminated (except for the ends of the interval) the estimation error is worse (40% error increase for one elimination):

$$f = \frac{1}{n-1} \sum_{1, k \neq k_0}^n y_k = \frac{x_n - x_{k_0} + x_{k_0-1} - x_0}{n-1}$$

$$\text{error on } f : \frac{2}{n-1} \sigma_x$$



If there is no cycle slip, it is better to have the complete continuity even if the measurement noise is important

1 cycle slip : 14.7 cm (2 GHz), 74.7 cm (400 MHz)
 15.3 cm , 3.0 cm (iono-free combination)

—————> Possible combined Doris cycle slips ?

Cycle slips and iono-free variations

f1	f2	(m)	f1	f2	(m)	f1	f2	(m)
<u>0</u>	<u>1</u>	<u>-0.030</u>	1	-1	0.183	2	4	0.186
0	2	-0.060	<u>1</u>	<u>0</u>	<u>0.153</u>	2	5	0.155
0	3	-0.091	1	1	0.123	2	6	0.125
0	4	-0.121	1	2	0.093	2	7	0.095
0	5	-0.151	1	3	0.063	2	8	0.065
0	6	-0.181	1	4	0.032	2	9	0.035
			<u>1</u>	<u>5</u>	<u>0.002</u>	<u>2</u>	<u>10</u>	<u>0.005</u>
			1	6	-0.028	2	11	-0.026
			1	7	-0.058	2	12	-0.056
			1	8	-0.088	2	13	-0.086
			1	9	-0.118	2	14	-0.116
			1	10	-0.149	2	15	-0.146
			1	11	-0.179	2	16	-0.177

f1 cycle slip
(case of high elevation measurements)

red values : below 15 cm (f1 cycle slip)

Lot of combinations are producing small variations on the iono-free combination
this is due to the frequency ratio, very close to 5 (543/107)

Not possible to handle correctly simultaneous cycle slips on the iono-free combination

hypothesis : no simultaneous cycle slip on frequency 2 (400 MHz)

Remaining error (for 2 GHz) on the iono-free combination

--> 15.3 cm	for 1 cy
--> 3.8 cm	for 0.25 cy
--> 2.6 cm	for 0.17 cy

(below the 1 cycle at 400 MHz)

This is robust to orbit errors

(1m --> 0.001 m/s --> 1 cm over 10 s, there is still a big margin to observe the cycle slip)

Set of measurements assumed without cycle slip are constructed using the iono-free combination

Not possible to handle correctly simultaneous cycle slips on the iono-free combination

hypothesis : no simultaneous cycle slip on frequency 2 (400 MHz)

Remaining error (for 2 GHz) on the iono-free combination

--> 15.3 cm	for 1 cy
--> 3.8 cm	for 0.25 cy
--> 2.6 cm	for 0.17 cy

(below the 1 cycle at 400 MHz)

This is robust to orbit errors

(1m --> 0.001 m/s --> 1 cm over 10 s, there is still a big margin to observe the cycle slip)

Set of measurements assumed without cycle slip are constructed using the iono-free combination

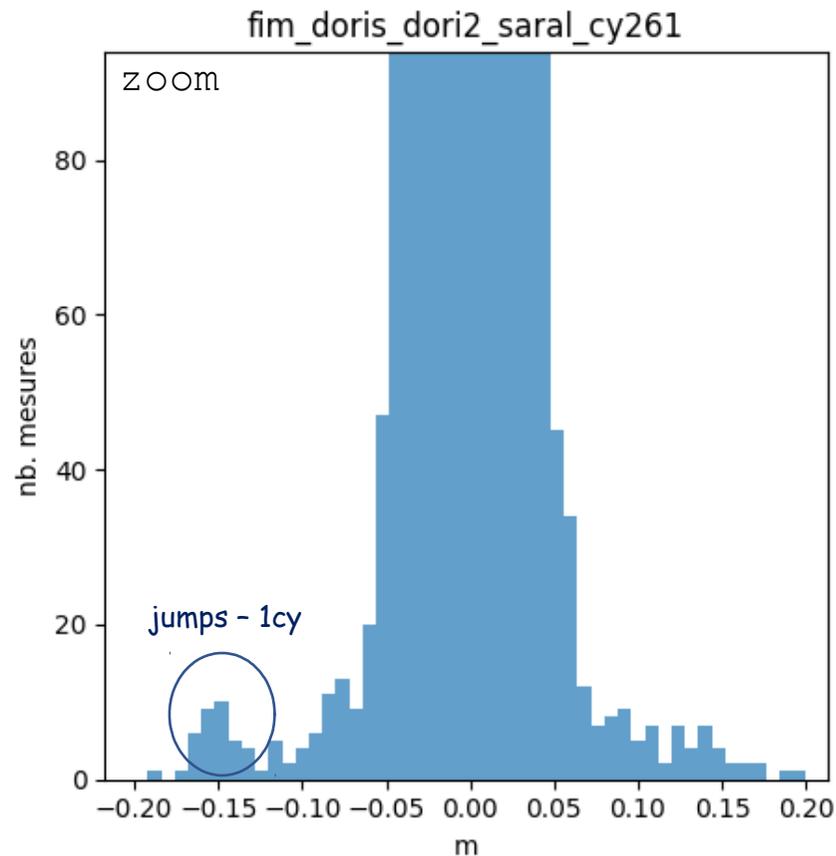
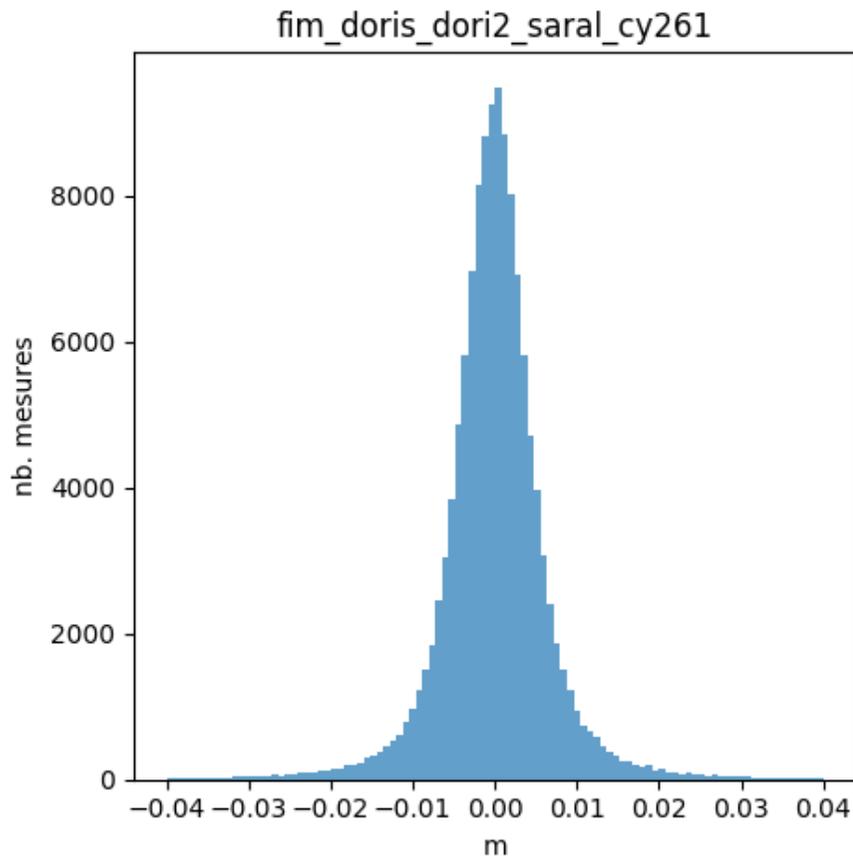
```
low Doppler : variation [0.75,1.25 cy] --> correction -1 cy 2 GHz
              variation [-1.25,-0.75 cy] --> correction 1 cy 2 GHz
anywhere     : variation more than 0.17 cy --> interruption
```

elevation above 5 degrees

more than 10 consecutive phase measurements

Raw residuals histogram (Saral)

No elimination
Phase variation residuals



Reconstruction : Saral cy 261, 2GHz cycles slips at low Doppler

```
reconstruction 64 : -0.966 cy, variation 747.4 cy
reconstruction 78 : -1.097 cy, variation -490.8 cy
reconstruction 184 : -1.130 cy, variation -275.2 cy
reconstruction 293 : -1.156 cy, variation 300.2 cy
reconstruction 319 : -1.066 cy, variation 74.4 cy
reconstruction 349 : -0.948 cy, variation -785.3 cy
.....
reconstruction 1962 : 0.876 cy, variation -241.2 cy
reconstruction 2076 : -0.984 cy, variation 86.6 cy
reconstruction 2084 : -0.911 cy, variation -877.3 cy
reconstruction 2230 : -0.848 cy, variation 300.8 cy
reconstruction 2286 : -0.884 cy, variation 857.9 cy
reconstruction 2318 : -1.097 cy, variation 348.6 cy
reconstruction 2372 : -0.993 cy, variation -766.5 cy
reconstruction 2383 : -0.909 cy, variation 851.9 cy
reconstruction 2491 : -1.106 cy, variation -713.8 cy
reconstruction 2496 : -0.933 cy, variation 633.8 cy
reconstruction 2567 : -0.877 cy, variation 527.7 cy
nombre de reconstructions fréquence centrale : 43
```

The jumps occur at low elevations : 43 here for a 9 days arc
(Cryosat, 2 to 3 jumps per day)

Almost always -1 cycle at 2GHz.

High residuals (phase variations) : few cases, easy to detect and remove

statistics for cycle 261 Saral,
all measurements
low Doppler measurements reconstructed

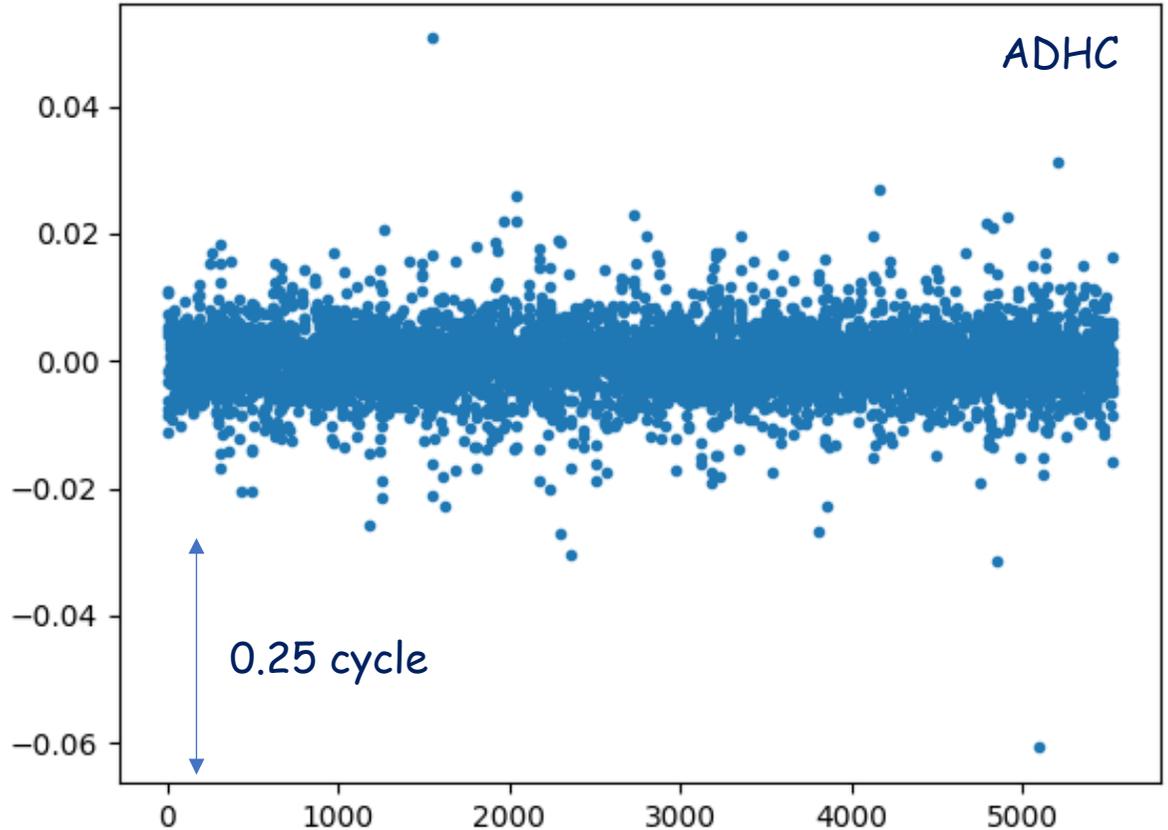
residual (m)	<0.1	<1	<10	<100	<1000
nb. tot. mes.	128588	128652	128666	128753	128768
nb. mes.		64	14	87	15

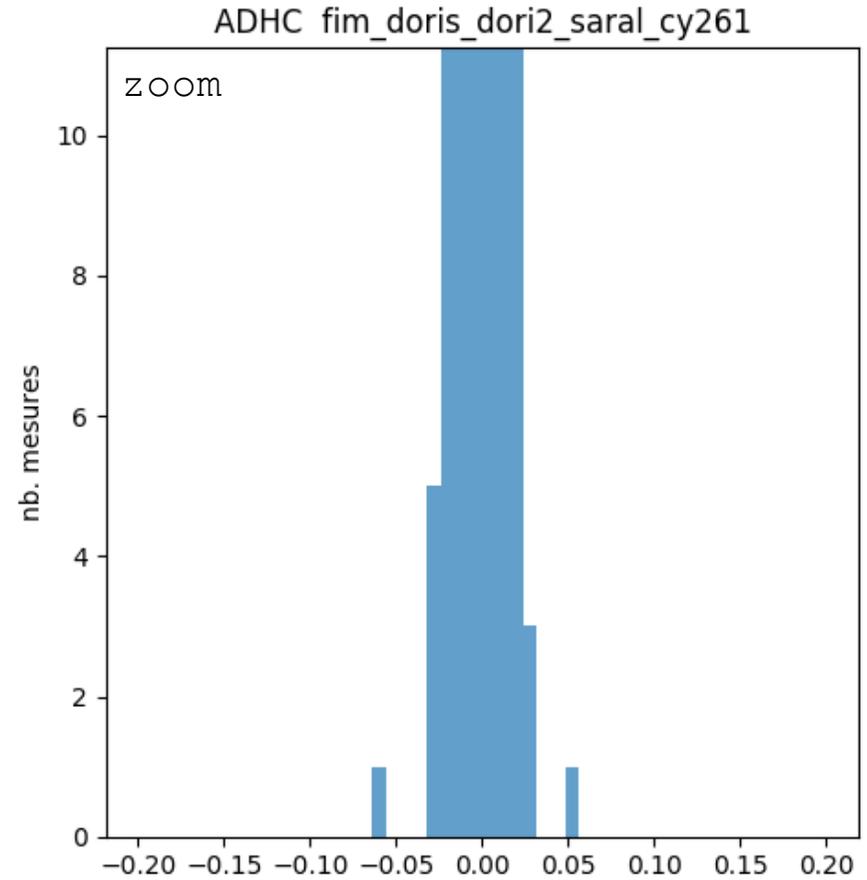
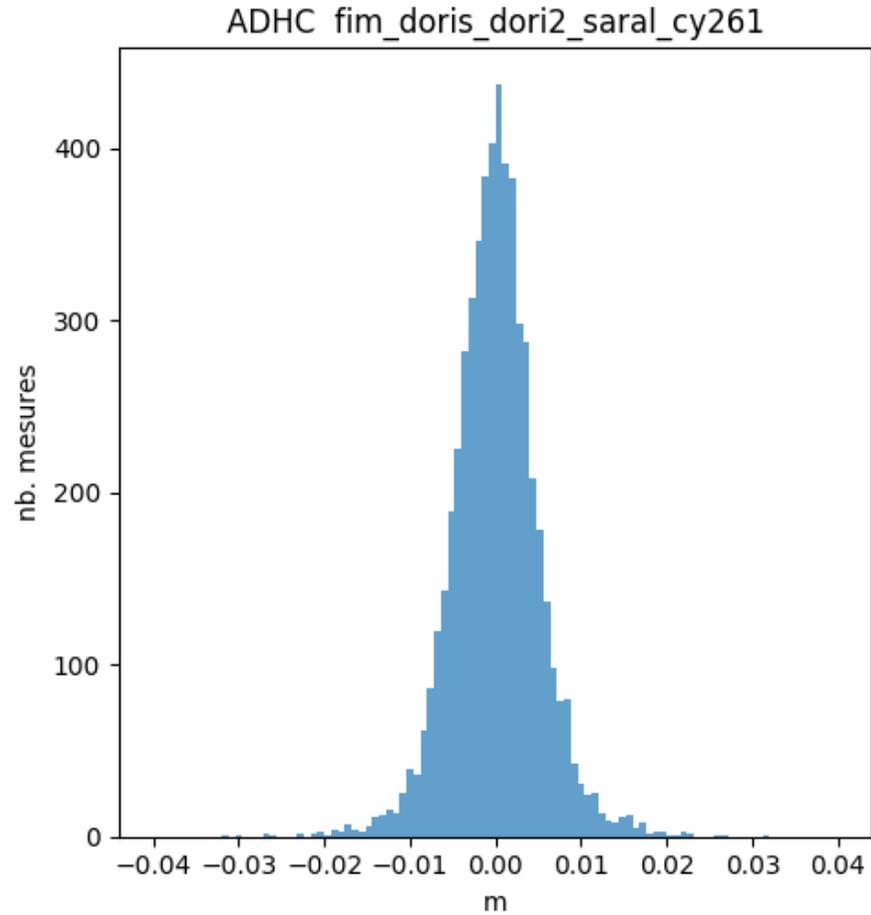
Phase variations over 10 s

All measurements, threshold 100 m

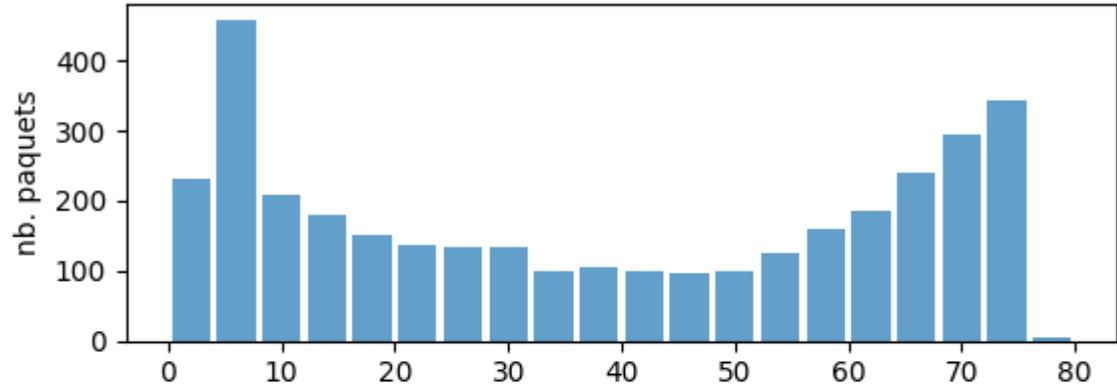


With 1 m threshold for example
we obtain correct measurements
(all variations are below 0.5 cycle)



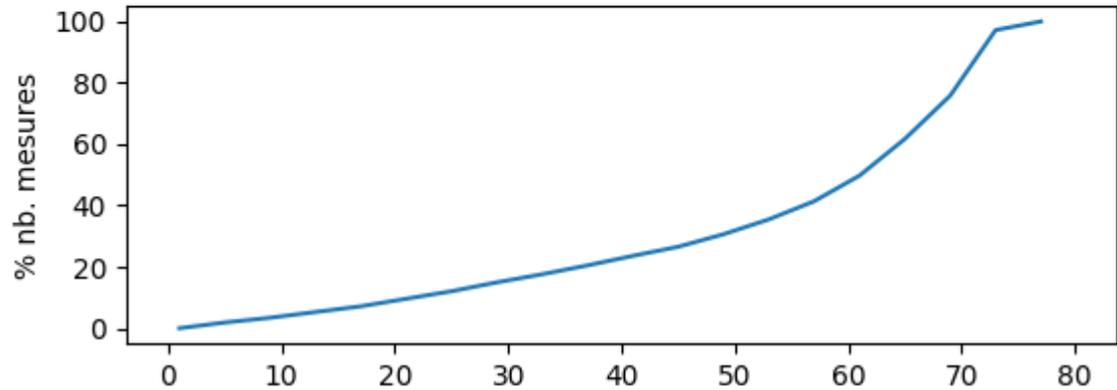


fim_doris_dori2_saral_cy261 histogrammes paquets

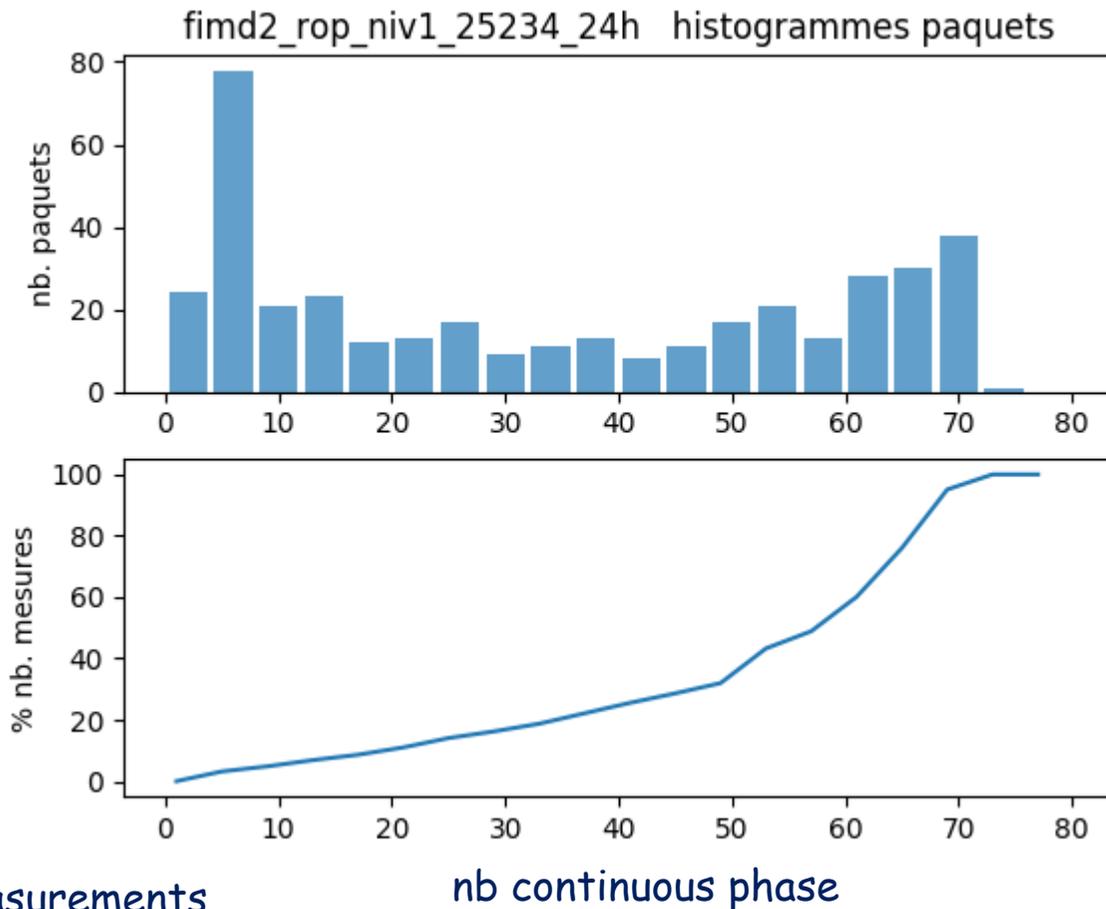


Sets below 10 measurements

- important number of cases
- less than 5 % of the total measurements



Continuous sets with more than 10 measurements

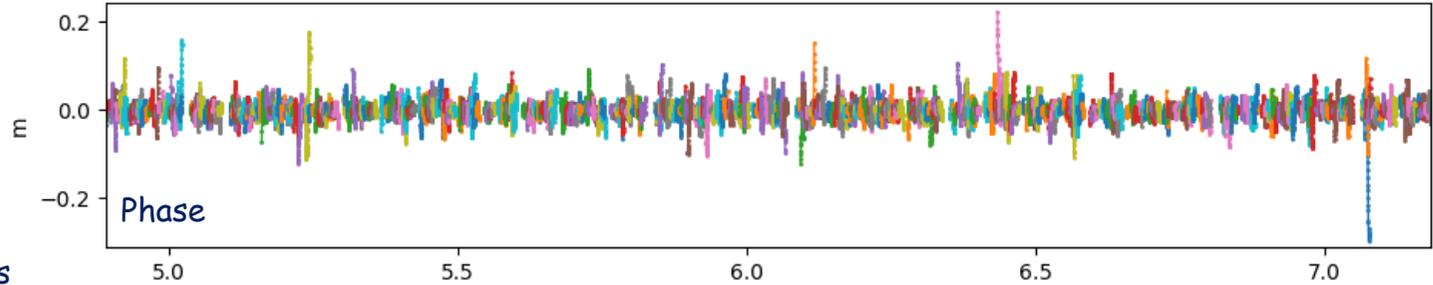


Continuous sets with more than 10 measurements

nb continuous phase

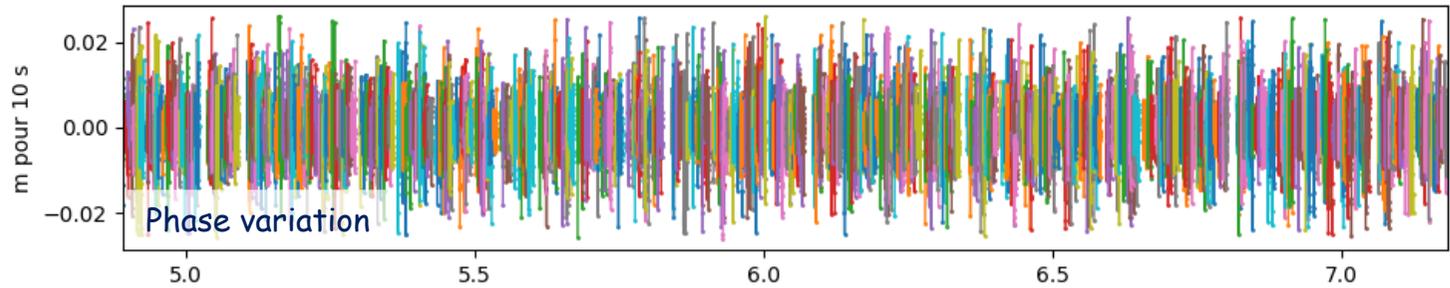
Saral residuals (POE)

fim_doris_dori2_saral_cy261 residus phase et incr. phase valides, par passage

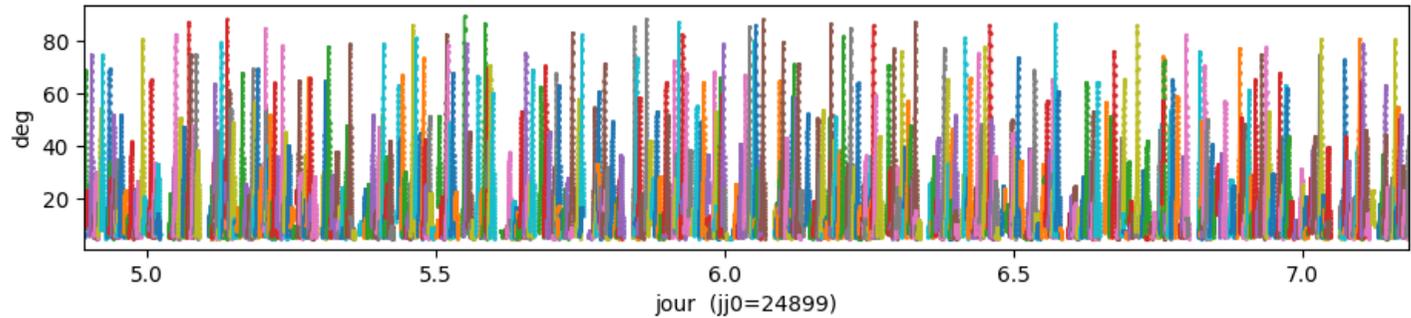


Threshold 2.6 cm over 10 s

rms phase variation
5.6 mm



Elevation > 5 deg

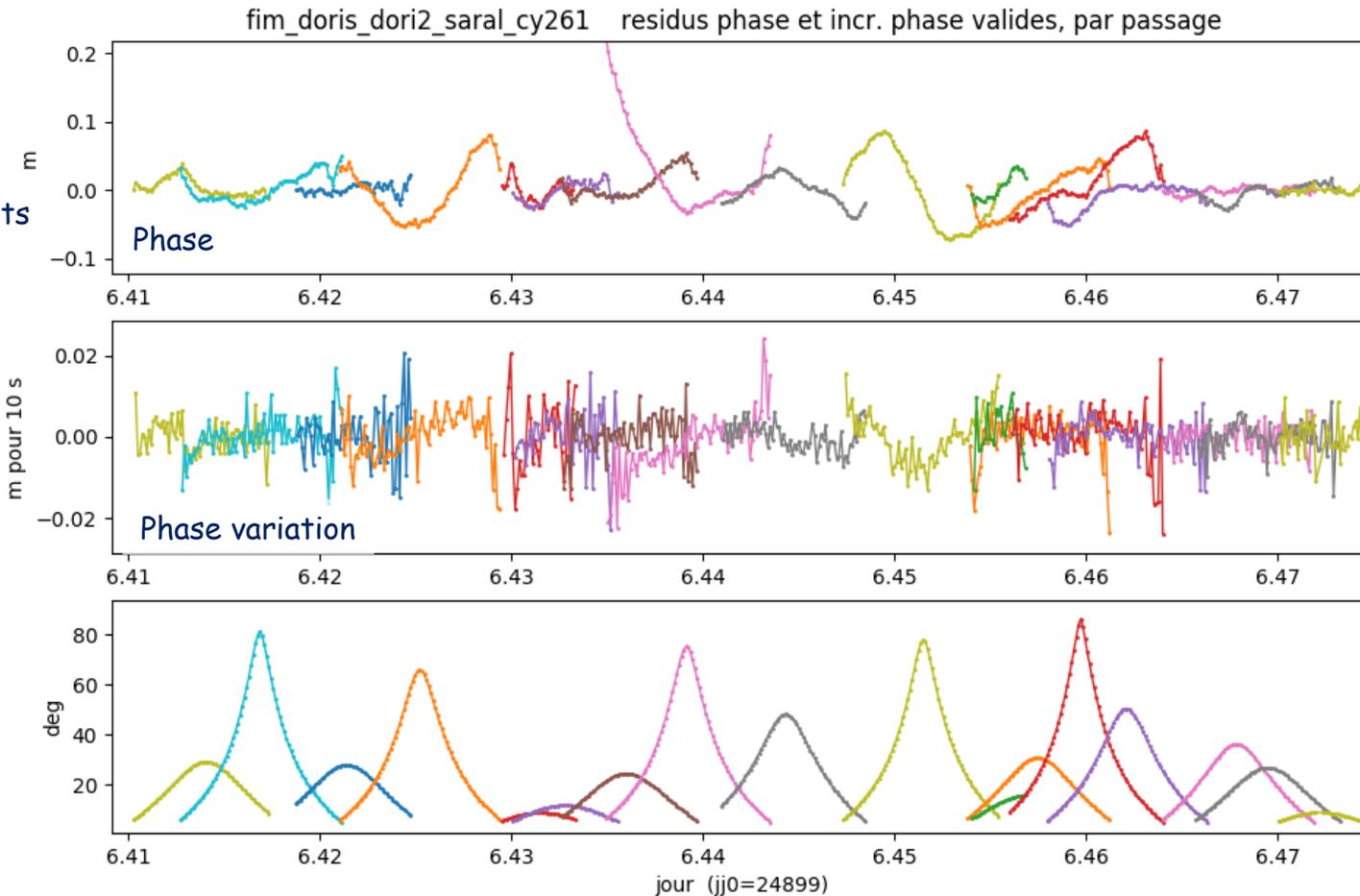


Almost all passes have measurements below 5 degrees

All information present in the residuals seems relevant

Remaining signatures

USO
troposphere
multipath
... ?



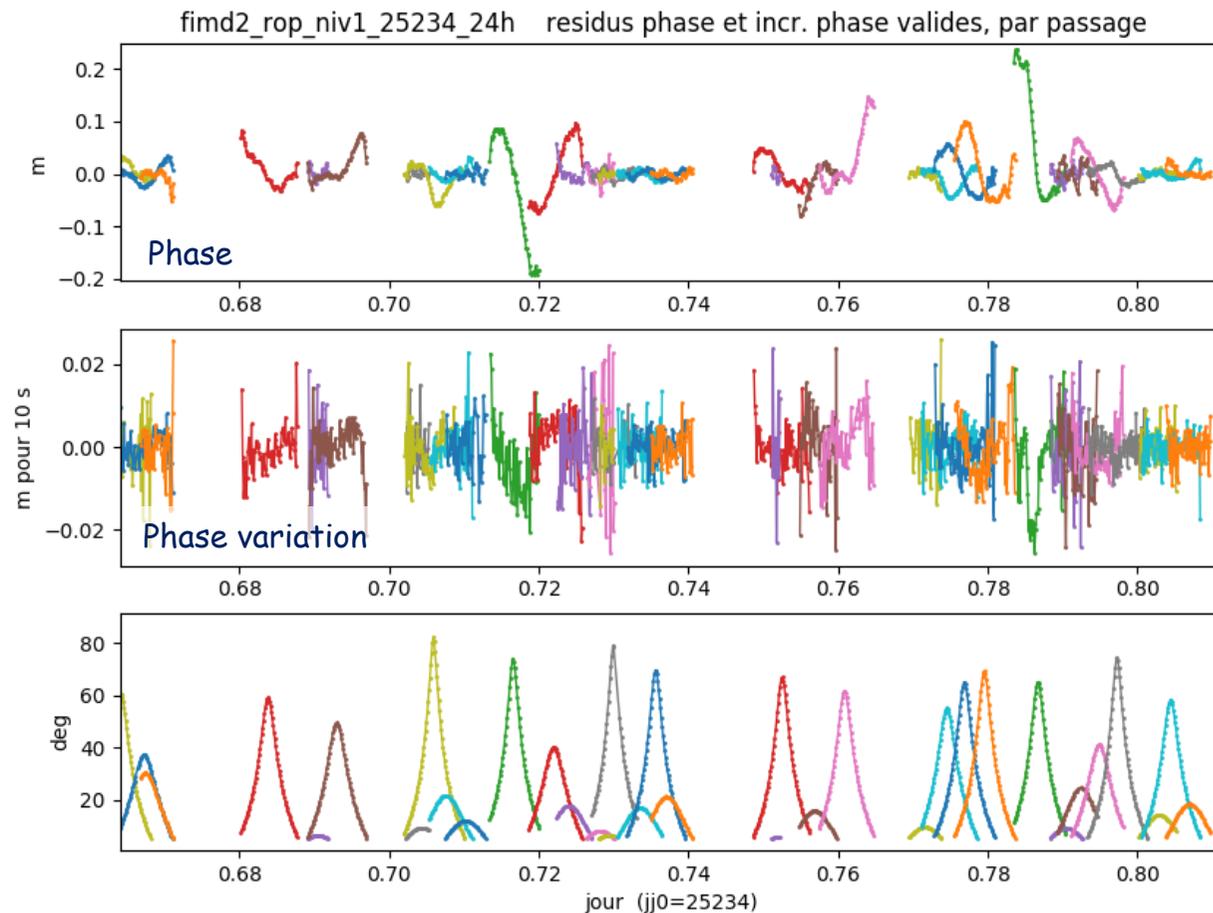
Almost all passes have measurements below 5 degrees

All information present in the residuals seems relevant

Rms phase variation 6 mm

Remaining signatures

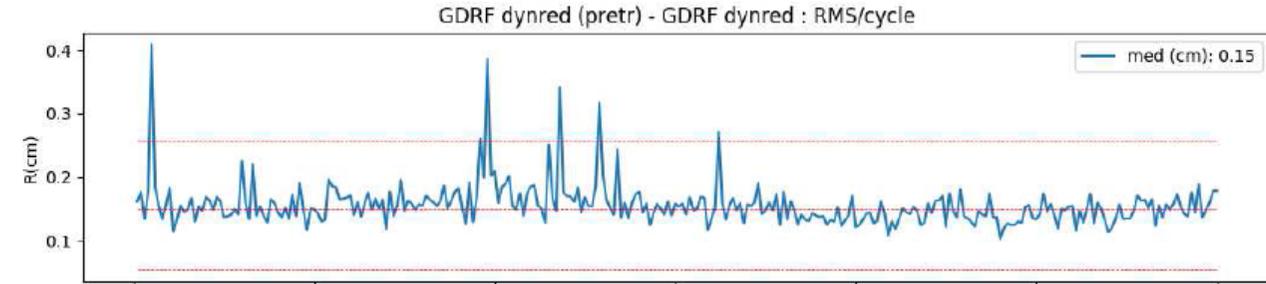
USO
troposphere
multipath
... ?



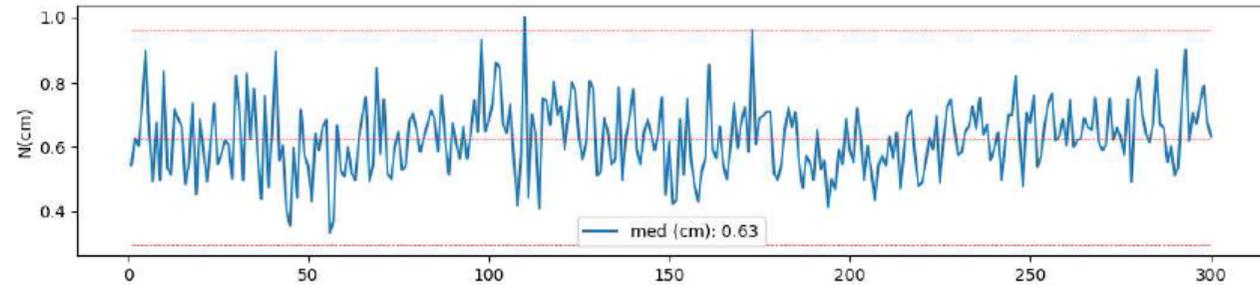
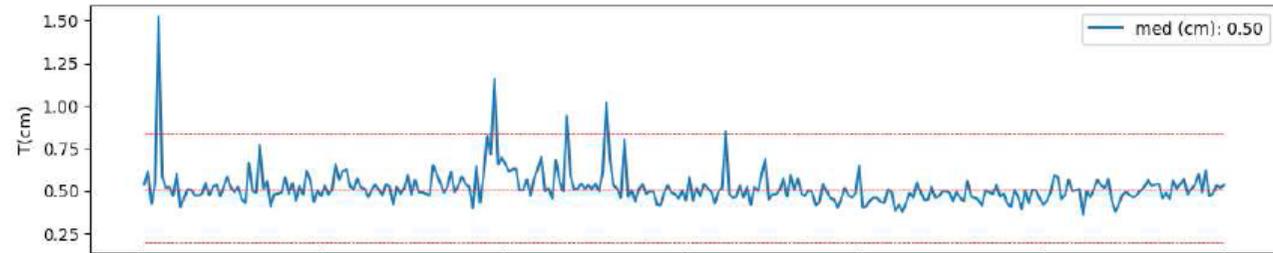
Orbit determination results on Saral and Cryosat

Reprocessing of Saral, orbit comparison

Difference with current solution
1.5 mm rms radial



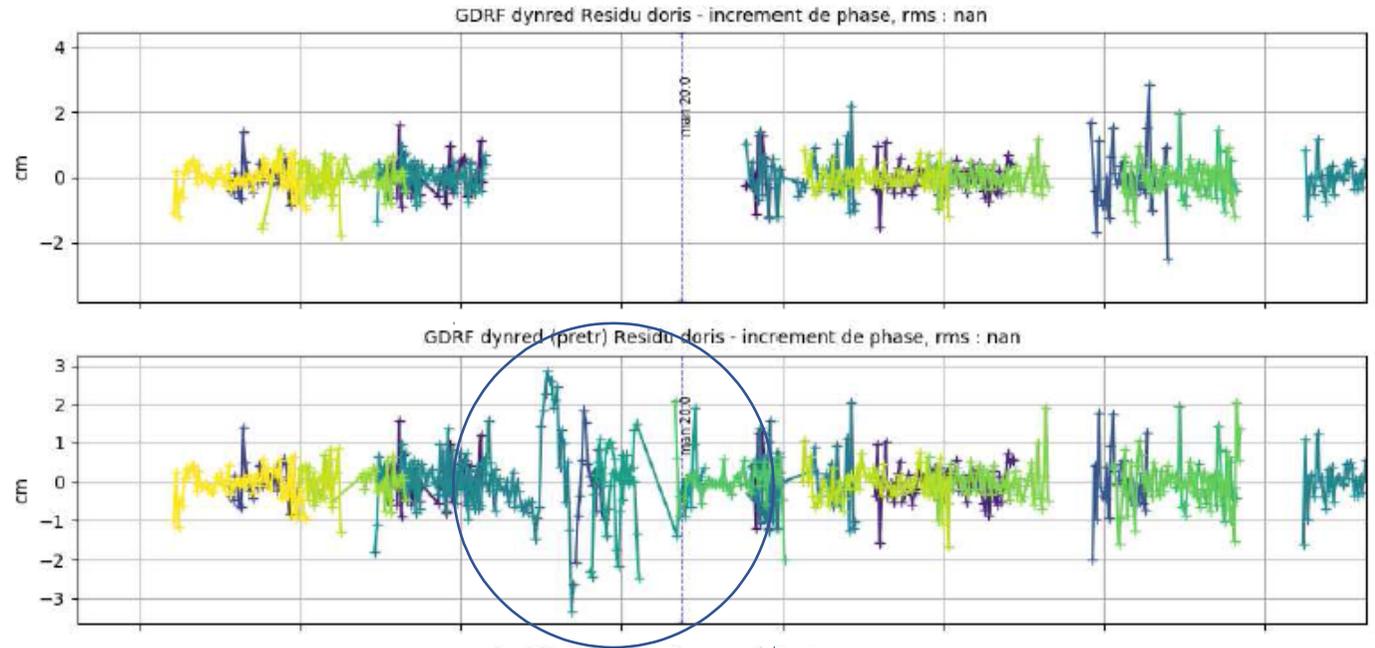
Some cycles are perturbed
due to manoeuvres



The new preprocessing is not too sensitive to the dynamic modelling errors

Some passes occur during the manoeuvre and the measurements are correct
But the model is not precise enough

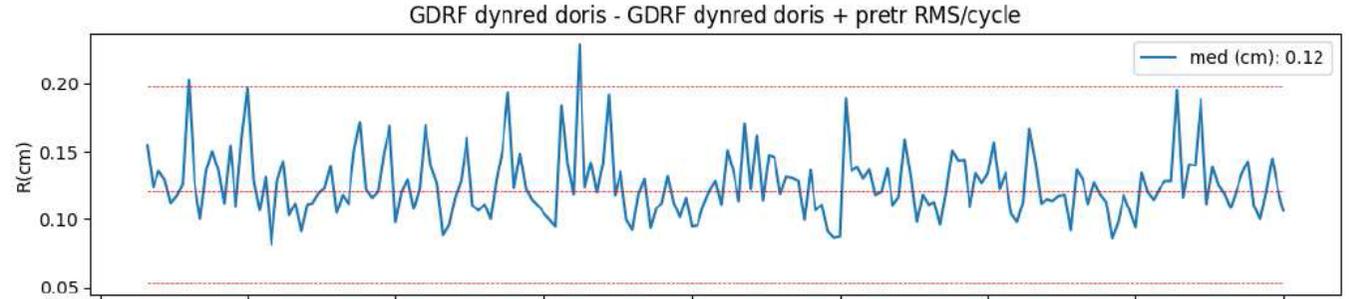
These data were eliminated in the standard processing
(rms residuals over a pass)



around the manoeuvre

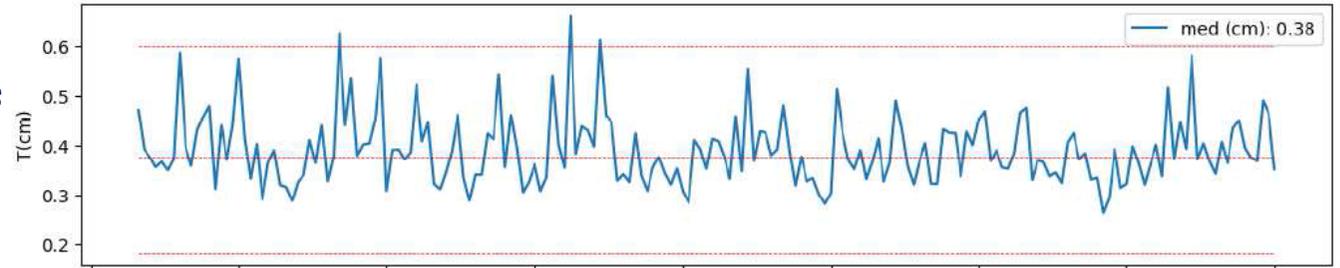
Reprocessing of Cryosat, orbit comparison

Difference with current solution
1.2 mm rms radial

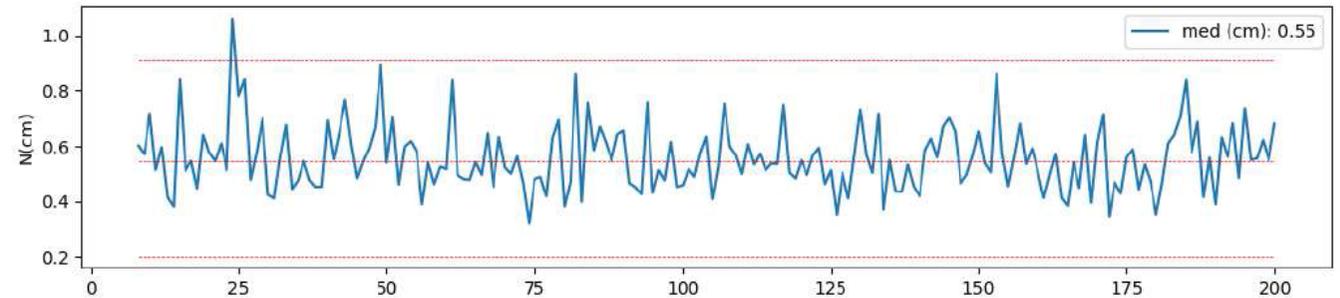


Like Saral, some orbits are perturbed
by isolated passes with important signatures
USO effect, SAA ?

(~1 cm in radial locally)

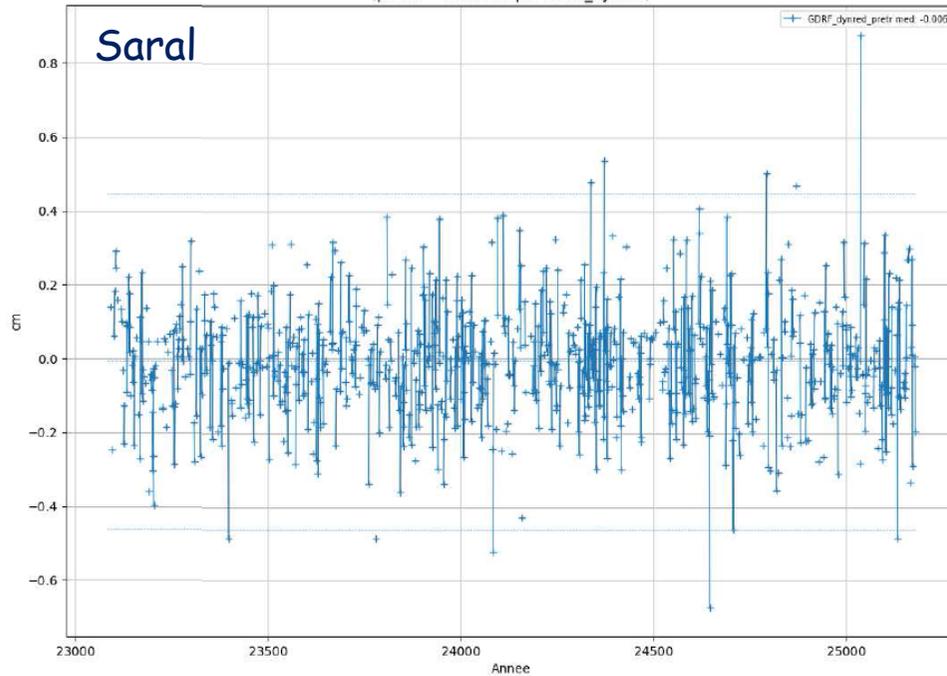


Some cycles are perturbed
due to manoeuvres

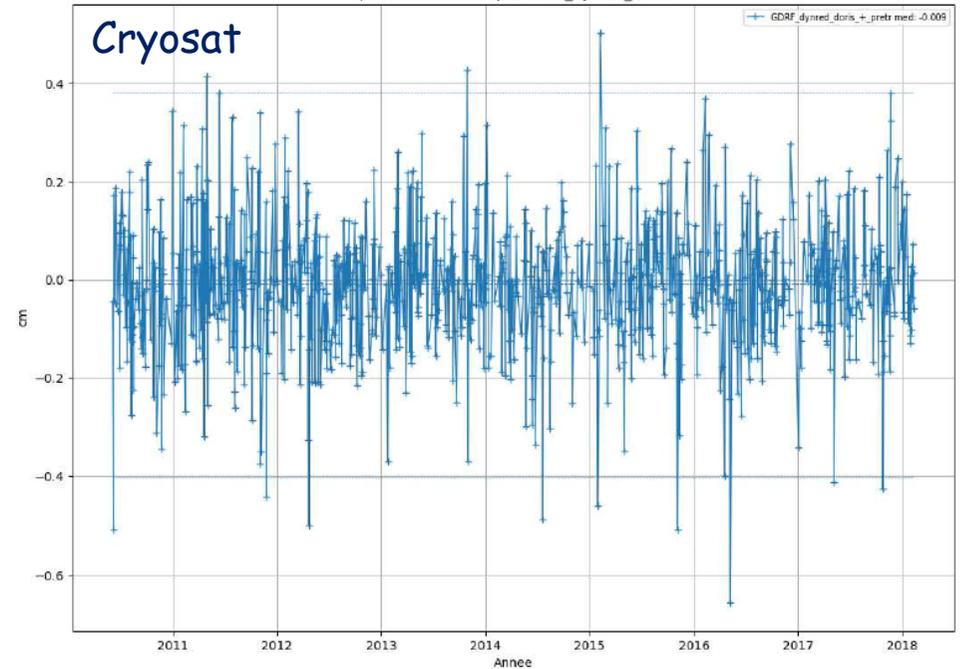


Global results, high elevation SLR residuals

RMS SLR: Core network - hautes elevations
(positif = meilleur que GDRF_dynred)



RMS SLR: Core network - hautes elevations
(positif = meilleur que GDRF_dynred_doris)



(>0 , better than current gdrf product)

High elevation SLR residuals : similar performance with the new processing

Conclusion

New preprocessing

- low Doppler measurements are used, cycle slip reconstruction
- 10 consecutive correct phase measurements minimum
- minimal elevation 5 degrees

Achieved radial accuracy : similar to current products

- effects for positioning ?
- pole and geocentre ?
- some passes with important signatures (manoeuvre, USO, attitude, others ?)

Less sensitive to orbit errors (0.25 cycles --> 3.8 cm variation over 10 s)

Combined cycle slips are still an issue

Preparation of future formulations (direct phase processing)

- phase maps (see Hanane presentation)
- USO, SAA studies
- orbits
-