

Doris ground antennas Radio Frequency characterization Status

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- **Reminder : Starec antenna characterization provided**
- **Analysis of dispersion w.r.t. azimuth angle**
- **CATR measurement error estimation**
- **DORIS ground antenna error budget**

Reminder

● Characterization provided for DORIS STAREC ground antennas

◆ 2GHz :

» Phase center : 487 mm above the reference plan

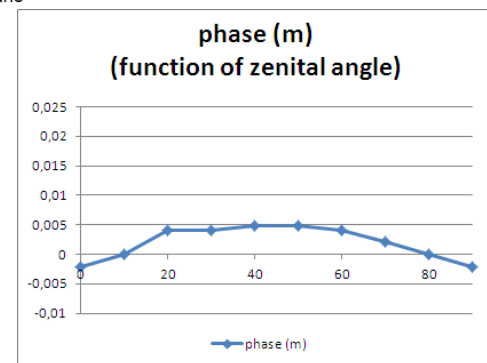
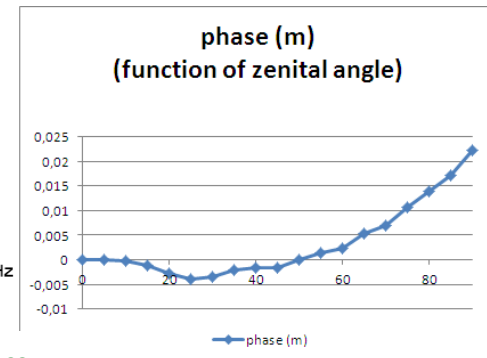
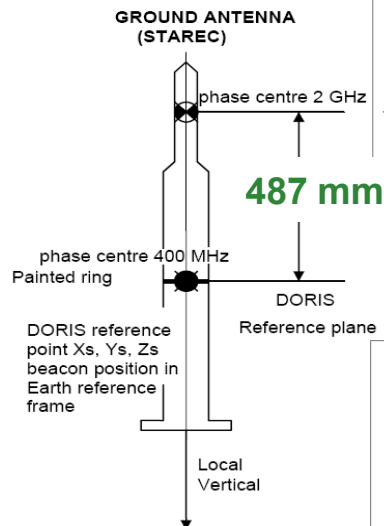
» 2Ghz Phase law :

◆ 400 MHz : no change

» Phase center: 0 mm above the reference plan

» 400Mhz Phase law

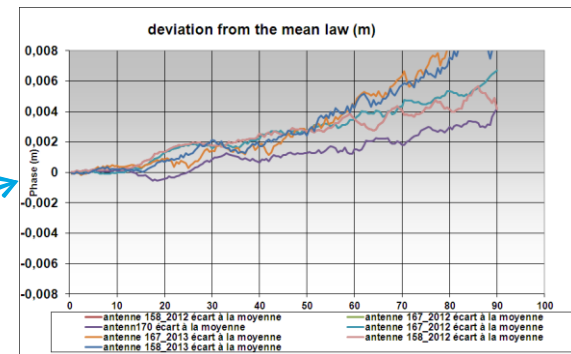
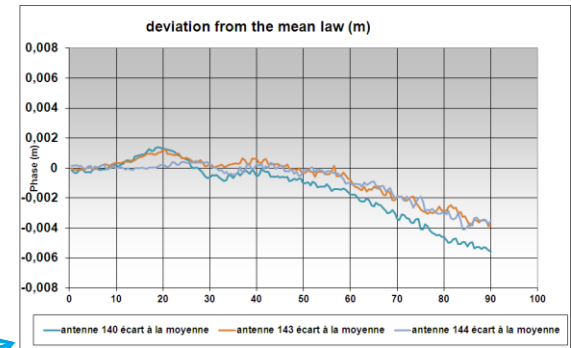
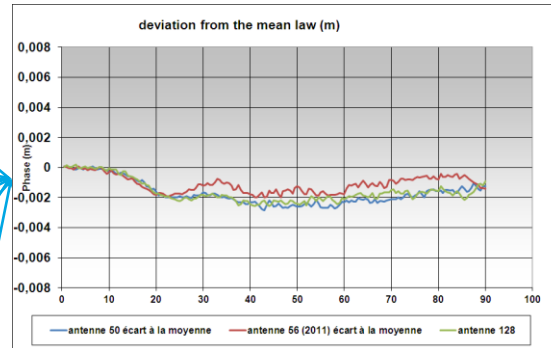
**Characterizations provided via antex files
(proper use described in specific slides)**



Antenna dispersion

- Antennas characterized at CNES compact antenna test range (CATR)
- In parallel, a set of antennas dismantled
 - ◆ Distance between 2GHz radiating element bottom and mounting flange (TCMA)

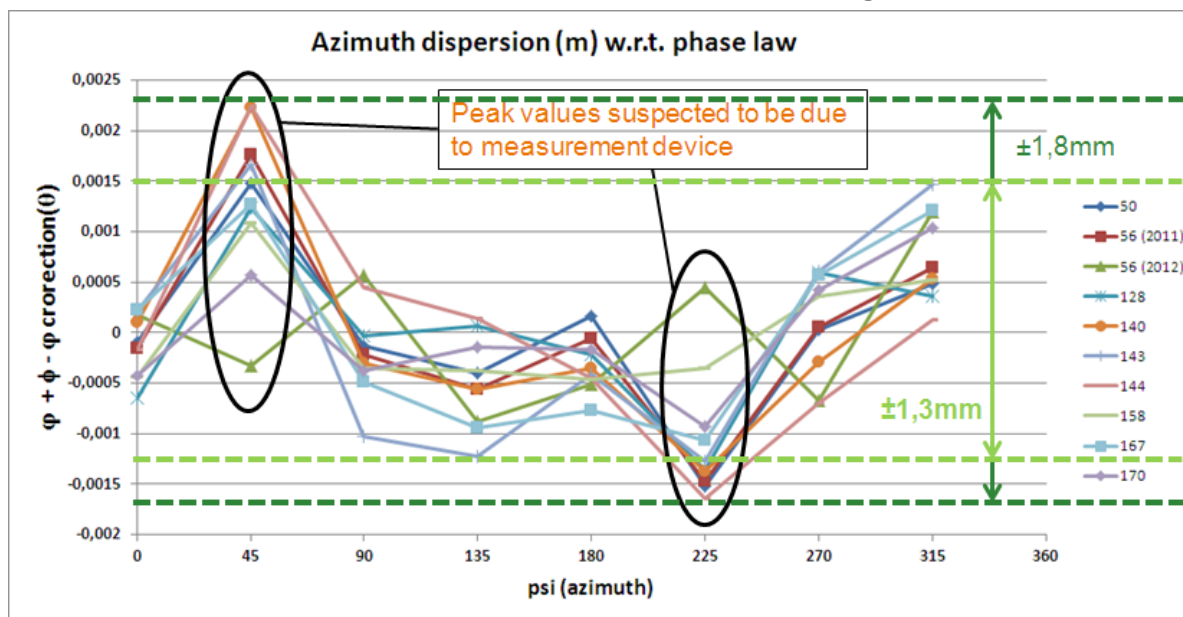
Batch	Antenna	TCMA (mm)
Starec	26	715
	50	715
	56	716
Juin 2000	61	710,5
Dec 2000 (64 80 82 85- > 134)	88	712
	90	712
	103	712
	118	713
	127	715
2006 (135-> 156)	128	
	140	
	143	
	144	
	149	714,5
2012 (157-> 170)	156	720
	158	
	167	
	170	713



- Distance corresponding to the mean law provided via antex files : 716mm
- Dispersion wrt this distance : -6mm /+4mm for old antennas (SN < 171)
- **Future antennas : distance guaranteed at 716 ±1mm (from SN 171)**

Analysis of dispersion w.r.t. azimuth angle first analysis (2/2)

- Usual analysis performed by the CATR Compact Antenna T Room
 - ◆ 9 antennas analyzed
 - » 4 plans (4 azimuth angle): $\phi = 0^\circ, 45^\circ, 90^\circ, 135^\circ$; with θ going from -180 to 180°
 - » 8 samples of azimuth measurements
- We get an estimation of the dispersion (θ averaged) :



- We observe an azimuthal dispersion of
 - ◆ $\pm 1,8\text{mm}$ including peak values

Analysis of dispersion w.r.t. azimuth angle

Second analysis (1/2)

Specific analysis performed at CATR

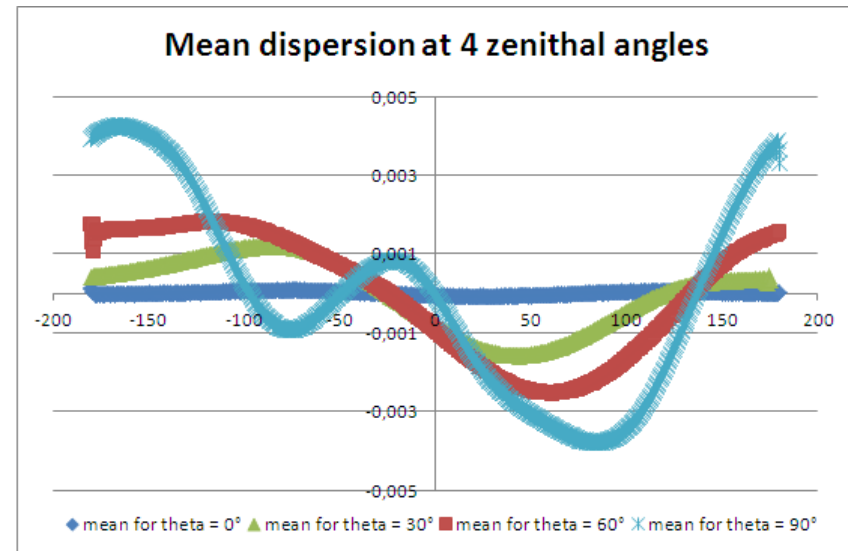
- ◆ 3 antennas analyzed :
 - » 4 plans (4 zenithal angle): $\theta = 0^\circ, 30^\circ, 60^\circ, 90^\circ$; with ϕ going from -180 to 180°
- ◆ To eliminate inter-antennas variability
 - » we determine the mean dispersion over all antennas
- ◆ mean azimuthal dispersion for 4 zenithal angles
- ◆ the mean over θ angle is $\pm 1,8\text{mm}$
 - ⇒ Consistent with first analysis

◆ Impact of dispersion :

- » Law θ values :
 - impact on the up component
 - small dispersion => small impact on up
- » High θ values :
 - impact on the N/E component
 - greater dispersion ($\pm 3,7\text{mm}$ at 85°)
 - => greater impact
 - for standard passes we can estimate a max impact of $\pm 3\text{mm}$

◆ This dispersion includes:

- » True Azimuthal RF dispersion
- » Perpendicularity / Coaxiality defaults of Antenna axis w.r.t. Mounting flange
- » Centering default of radiating elements
- » CATR eventual default, rotation axis perpendicularity



θ	Max dispersion
0°	0 mm
30°	$\pm 1,4\text{mm}$
60°	$\pm 2,15\text{mm}$
85° (interpolation)	$\pm 3,7\text{mm}$
90°	$\pm 4\text{ mm}$

Antenna axis eventual defaults

misalignment

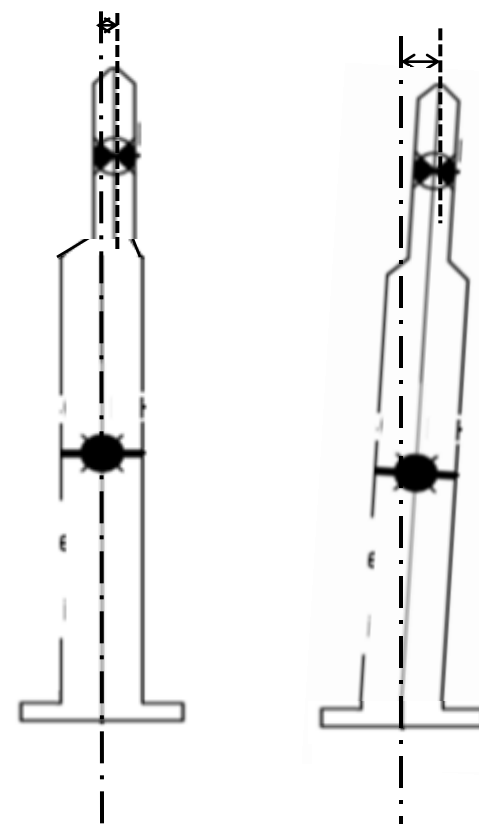
perpendicularity

✦ Misalignment / perpendicularity defaults

- » Now controlled by manufacturer on a machine tool w.r.t. mounting flange (plane&axis)
- » The error due to non perpendicularity or misalignment does not exceed : $\pm 0,5\text{mm}$ at antenna extremity

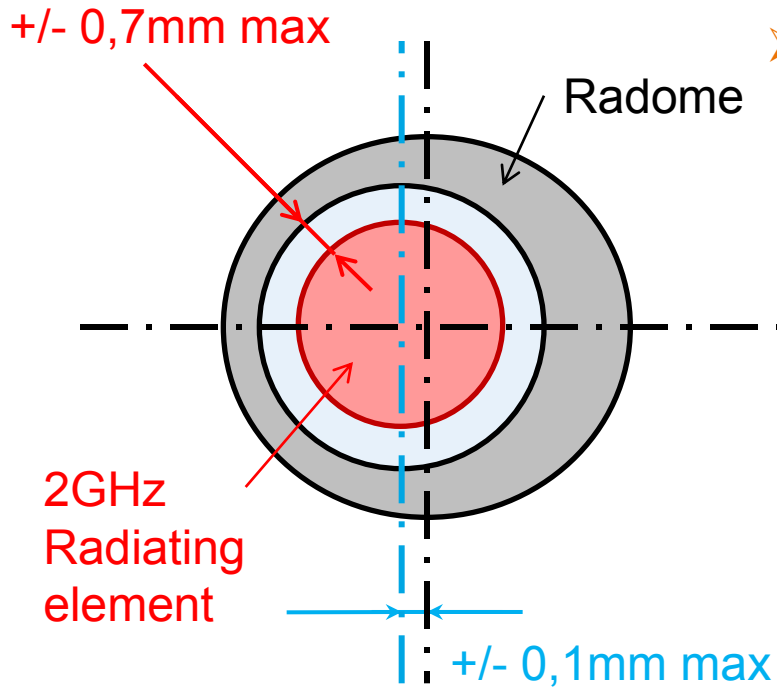
=> This implies an error in the horizontal plane

$\approx \pm 0,5\text{mm}$ of 2GHz phase center position N/E



Centering default of 2GHz radiating elements

- Perpendicularity of the radome external skin axis is controlled by the manufacturer with respect to mounting flange
- Remaining internal / external discrepancies
 - Irregularity of radome thickness
 - clearance between radiating elements and radome

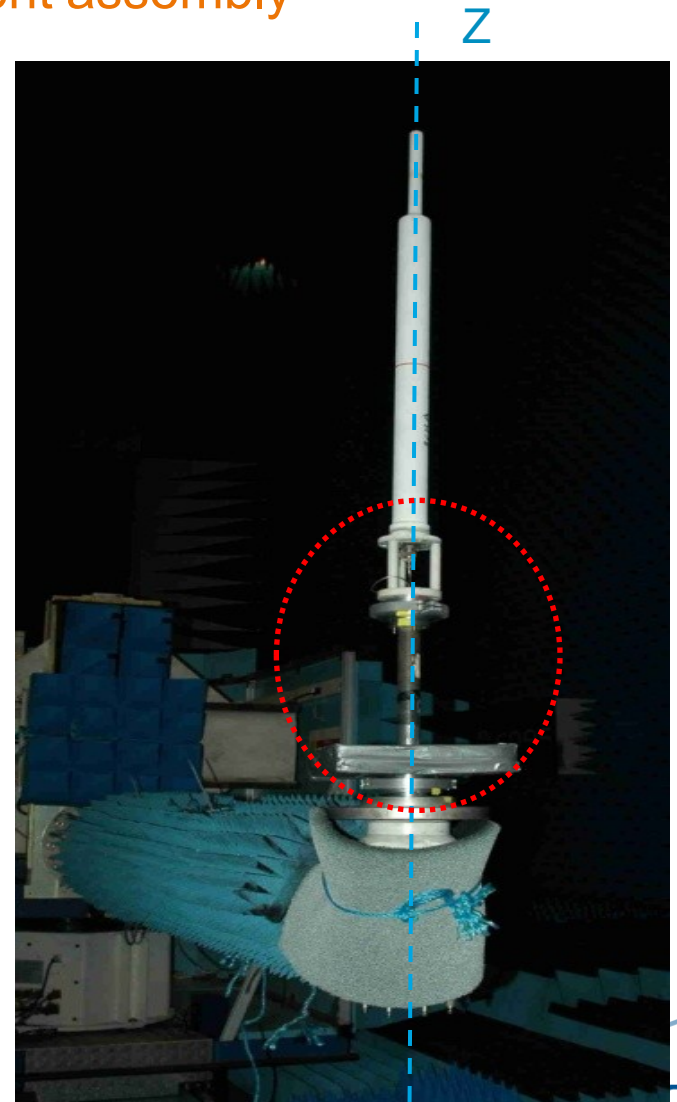
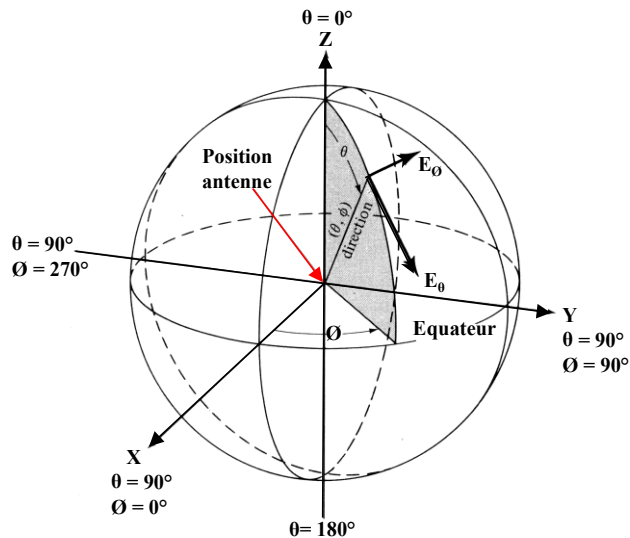


Discrepancy between internal axis and radome external surface	$\pm 0,1\text{mm}$
Gap between radiating element and internal radome surface	$\pm 0,7\text{mm}$
total	$\pm 0,8\text{mm N/E}$

Antenna perpendicularity default in CATR

Perpendicularity default due to measurement assembly

- ♦ Antenna aligned on Z axis of measurement device
- ♦ Antenna is set on measurement device thank to mechanic interface
 - » Perpendicularity is not totally perfect
 - » Default assumed : $\pm 1 \text{ mm}$ at 2GHz height (887mm)



Analysis of dispersion w.r.t. azimuth angle

Conclusion

- The two analysis performed lead to the same result :
 - ◆ A maximum azimuthal dispersion of $\pm 1,8\text{mm}$ (theta averaged)
- The worst impact of azimuthal dispersion would be $\pm 3\text{mm}$ in horizontal plane (N/E), assuming the dispersion is totally due to antenna
 - ◆ But $\pm 1\text{mm}$ is probably due to CATR measurement assembly
- This allows to establish the following azimuth error budget

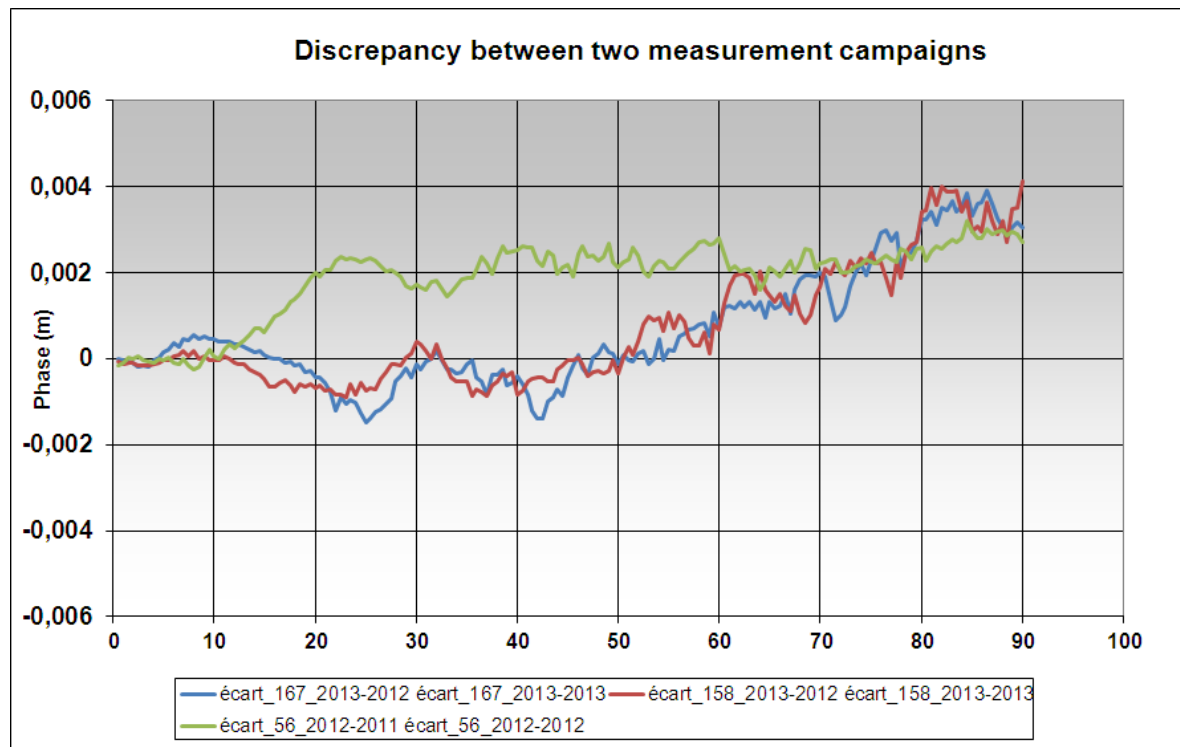
Antenna Azimuth error budget	
Error source	N/E impact
Total observed	$\pm 3\text{ mm}$
CATR assembly	$\pm 1\text{ mm}$
=> Total antenna	$\pm 2\text{ mm}$
Perpendicularity	$\pm 0,5\text{ mm}$
Centering	$\pm 0,8\text{ mm}$
=> Azimuth phase pattern variation	$\pm 0,7\text{ mm}$



- We assume the DORIS STAREC antenna is non azimuth dependent
 - ◆ Not really a surprise, STAREC antenna is helicoidal, it has a revolution symmetry by conception

The CATR has its own measurement error

- To get an estimation of this error
 - ◆ Some antennas characterized twice at CATR at 3 different epochs
 - ◆ Measurement discrepancy observed : 4mm max



⇒ We assume a **CATR measurement noise error** of **±2mm (up)**

DORIS Ground antenna error budget

Error source	up	plan (N/E)
Antennas variability (2GHz phase center position) before consolidation with manufacturer (SN < 171)	+4/-6 mm	
Antennas variability (2GHz phase center position) after consolidation with the manufacturer (From SN 171)	±1 mm	
Antenna characterization error (BCMA)	±2 mm	
Azimuthal dispersion (including RF, perpendicularity, centering)	0mm	± 2mm
<u>Total antenna alone</u>		
SN < 171	+6/-8 mm max 5,4 mm rms	± 2 mm max 0,7 mm rms
From SN 171	± 3 mm max 1 mm rms	± 2 mm max 0,7 mm rms
Antenna environment impact	TBD	TBD

Conclusion

- **Antenna alone is now well characterized**
- **Future work :**
 - ◆ **Environment impact**
 - ◆ **Satellite antenna Characterization**

THANK YOU

Backup slides

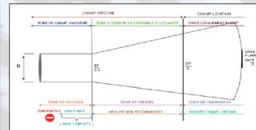
BASE COMPACTE DE MESURES D'ANTENNES

Objectifs : Connaître et maîtriser le rayonnement des antennes seules et sur structures



Chambre anéchoïque faradisée :
22 m x 12,5 m x 12 m

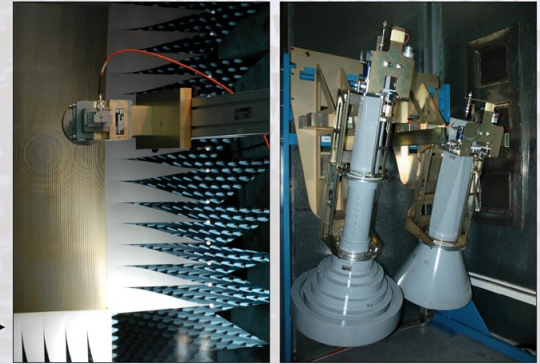
Simuler la distance satellite sol



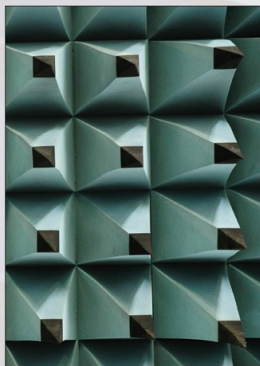
- ◀ Réflecteur parabolique :
5,3 m x 5,6 m, 48 tonnes.
- Focale : 13 m.
- Etat de surface : 25 µm RMS,
- Zone tranquille maximale
de 4 m x 4 m x 4 m.

15 sources primaires ▶
de 0,4 à 200 GHz.

Simuler la liaison bord sol



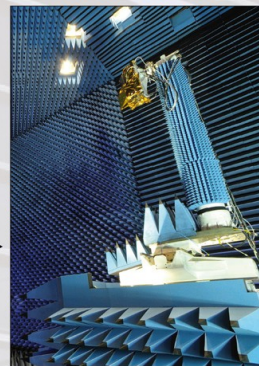
Isoler l'antenne dans l'espace



- ◀ Absorbants : -70 dB
de réflectivité typique
à 8 GHz.

Positionneur : 7 degrés ▶
de liberté en rotation
et translation.
Capacité : 350 Kg maximum.

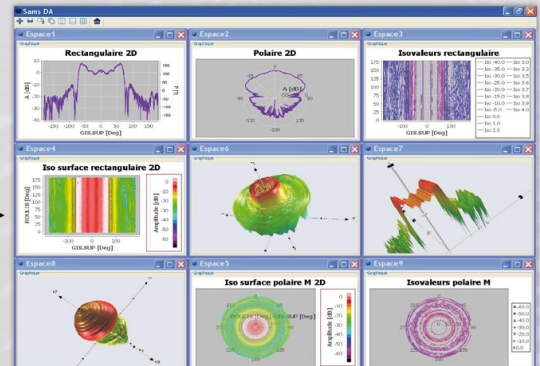
Positionner l'antenne dans l'espace



- ◀ Diagramme de rayonnement,
directivité, gain, localisation
centre de phase, temps de
propagation de groupe.
Performances système,
surface équivalente radar.

Instrumentation : analyseurs ▶
de réseau Agilent et
ABmillimètre, logiciels CNES/
SILICOM d'acquisition et
post-traitement.

Réaliser les mesures avec précision



Analysis of dispersion w.r.t. azimuth angle first analysis (1/2)

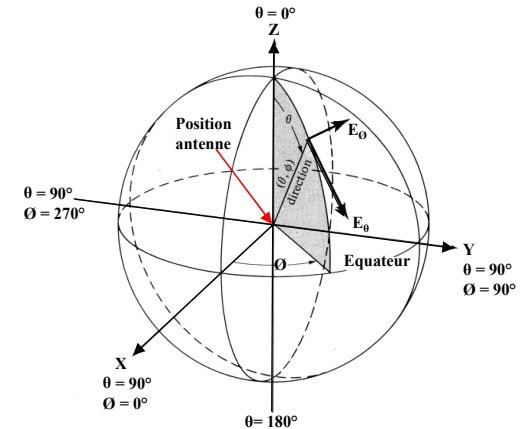
- ◆ 9 antennas analyzed
- ◆ Usual analysis performed by the CNES antenna department give :

Measurements for :

**4 plans (4 azimuth angle): $\phi = 0^\circ, 45^\circ, 90^\circ, 135^\circ$
with θ going from -180 to 180°**

- ◆ We can get 8 samples of azimuth measurements:

- | | |
|---------------------------------------|--|
| ● $\phi = 0^\circ; 0 < \theta < 90$ | ● $\phi = 0^\circ; 0 > \theta > -90 \Rightarrow \phi = 180^\circ; 0 < \theta < 90$ |
| ● $\phi = 45^\circ; 0 < \theta < 90$ | ● $\phi = 45^\circ; 0 > \theta > -90 \Rightarrow \phi = 225^\circ; 0 < \theta < 90$ |
| ● $\phi = 90^\circ; 0 < \theta < 90$ | ● $\phi = 90^\circ; 0 > \theta > -90 \Rightarrow \phi = 270^\circ; 0 < \theta < 90$ |
| ● $\phi = 135^\circ; 0 < \theta < 90$ | ● $\phi = 135^\circ; 0 > \theta > -90 \Rightarrow \phi = 315^\circ; 0 < \theta < 90$ |



- ◆ For each antenna, we calculate :

» For a given couple ($\phi; \theta$) :

» $\varphi - \phi - \varphi_{\text{correction}}(\theta)$

With : φ : phase measurement

ϕ : azimuth angle

$\varphi_{\text{correction}}(\theta)$: phase law correction

» To eliminate dispersion in θ

» we determinate the mean value over θ

=> We obtain a azimuthal dispersion for each antenna

