

Lessons from ITRF2008 and future considerations



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Lessons from ITRF2008

- **Technical Considerations:**
 - Impact and usage of local ties in ITRF combination
 - ITRF2008 accuracy
- **Structural Considerations**
 - Schedule to be agreed upon and respected for next ITRF solution
 - ITRF PC role

Consistency btw local ties and space geodesy estimates

- **GPS is linking SLR, VLBI & DORIS because**
 - VLBI-SLR alone: **8 co-locations only**
 - VLBI or SLR-DORIS alone : **10 co-locations only**
- **Tie discrepancies < 6 mm for:**
 - 47% GPS-VLBI
 - 43% GPS-SLR
 - 34% GPS-DORIS
- **Tie discrepancies > 10 mm for:**
 - 30% GPS-VLBI
 - 30% GPS-SLR
 - 54% GPS-DORIS

Scale and weighting of local ties

Scales with respect to VLBI (ppb) at 2005.0

| Case | SLR | DORIS | GPS | VF ¹ | Tie handling |
|--------------------------|---------------------|---------------------|--------------------|-----------------|--|
| ITRF2008 | -1.05 ± 0.13 | 0.18 ± 0.20 | 0.67 ± 0.10 | 0.90 | All tie SINEX files, weighted |
| ITRF2008 without EOPs | -1.11 ± 0.26 | 0.04 ± 0.31 | 0.41 ± 0.19 | 1.66 | All tie vectors, weighted |
| Case-1 | -1.20 ± 0.16 | -0.31 ± 0.34 | 0.49 ± 0.14 | 4.00 | Selection of local ties, $\sigma = 1$ mm |
| Case-2 | -1.02 ± 0.31 | -0.30 ± 0.84 | 0.52 ± 0.31 | 31.70 | Selection of local ties, $\sigma = 0.1$ mm |
| Case-3 | 0.0 ² | 0.48 ± 0.32 | 1.28 ± 0.08 | 4.28 | Same as Case-1 |

¹ Variance Factor

² parameter eliminated from the normal equation; assumed to be equal to VLBI scale

Accuracy of ITRF2008 Origin

- Defined by SLR only
- Agreement with ITRF2005
 - 4.7 mm in Z-translation at epoch 2005
 - 0.3 mm/yr drift in X-translation
- ==> “Accuracy”: 1 cm over the time-span of SLR observations

Accuracy of ITRF2008 Scale

- Defined by the average of VLBI and SLR
- Difference btw the two technique solutions:
 - 1.05 ppb at epoch 2005.0
 - 0.049 ppb/yr
- ==> “Accuracy”: 1.2 ppb (8 mm) over the common time-span of VLBI and SLR observations

Uncertainties of the Transfer of SLR origin and SLR&VLBI mean scale to GPS frame

| Ties used | TX mm | TY mm | TZ mm | Scale mm |
|---|------------------|------------------|------------------|---------------------|
| Ties – SG Discrepancies < 6 mm | 2.5 | 2.5 | 2.5 | 1.4 |
| Ties – SG Discrepancies < 10 mm | 1.4 | 1.1 | 1.2 | 1.2 |
| All – SNX ITRF2008 | 0.6 | 0.5 | 0.6 | 0.6 |

Conclusion of Technical Considerations

- **Local ties:**
 - All available ties should be used with proper weighting
 - The more ties used the more precise is the estimation
- **Accuracy of ITRF2008 origin&scale: ~ 1 cm**
 - Origin: ~ 1 cm
 - Scale : 1.2 ppb
- **Technique-specific systematic errors**
 - GPS uncalibrated radome
 - VLBI antenna gravitational deformations
 - SLR range/timing biases
 - DORIS beacon reference point behavior ?

Structural Considerations (1/2)

- **Avoid repeating the ITRF2005 and ITRF2008 dilemma:**
 - Harmful for IERS and the Technique Services
 - Users are confused and get less confident on IERS/ITRF
- **Given the estimated ITRF2008 accuracy (~1 cm):**
 - difference between IGN and DGFI solutions is less than 1 cm
 - despite DGFI unrealistic assumptions

Structural Consideration (2/2)

- IERS should take its responsibility and decide according to the agreed structure:
 - IERS has a mission of providing unique set of reference products
 - **Reasonable and agreed schedule should be observed and respected for next ITRF solutions**
 - Avoid soliciting the technique services to decide instead of IERS
 - **Enforce the ITRF PC role ==> will improve the IERS image**
 - **ITRF PC solution is the official IERS standard solution, unless DGFI (or other groups) demonstrate something superior, but this did not happen for two times in the past**
 - Encourage DGFI (& other groups) to do combinations
 - **ITRFyy should reflect an IERS label and be unique**
==> request that DGFI names its TRF solutions differently, e.g. DGFI2008 or something similar